



# **Katz und Maus – Kameratests im Wandel der Zeit**

Uwe Artmann

Image Engineering GmbH & Co KG





- **Kameras werden besser – Messverfahren müssen mithalten**
- Neue Technologien erfordern neue Messverfahren
- Was der Kunde nicht weiß... Den Finger in die Wunde legen





# Objektive Tests

# 1997



Image Engineering Diemtar Wüller  
Erster Digitalkameratest für ColorFoto



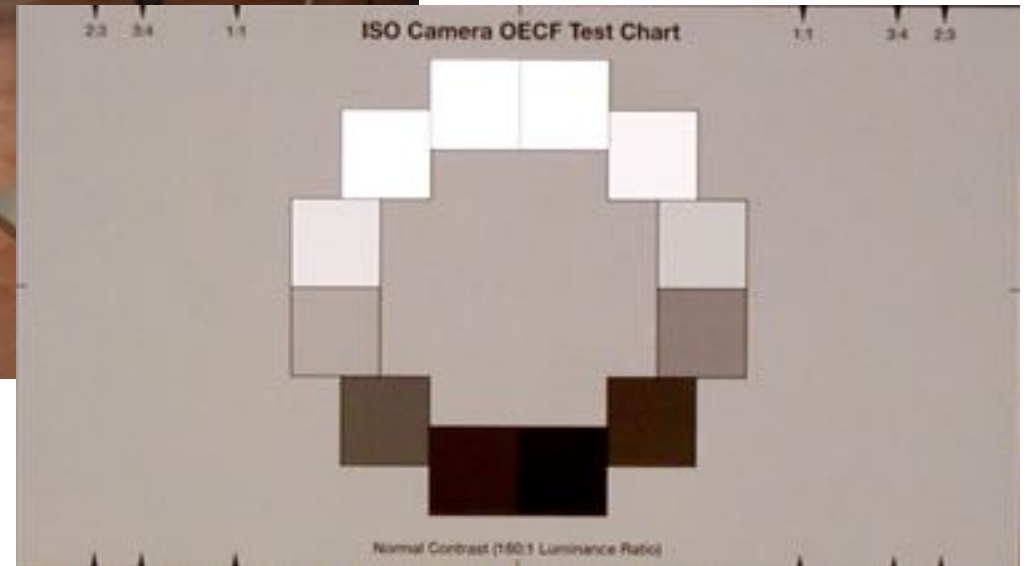


# Objektive Tests

# 1998



Image Engineering Diemtar Wüller  
Erster Digitalkameratest für ColorFoto





# Objektive Tests


## 2004



“Image Engineering Diemtar Wüller”  
Komplett digitaler Objektivtest





 The image part with relationship ID rld2 was not found in the file.

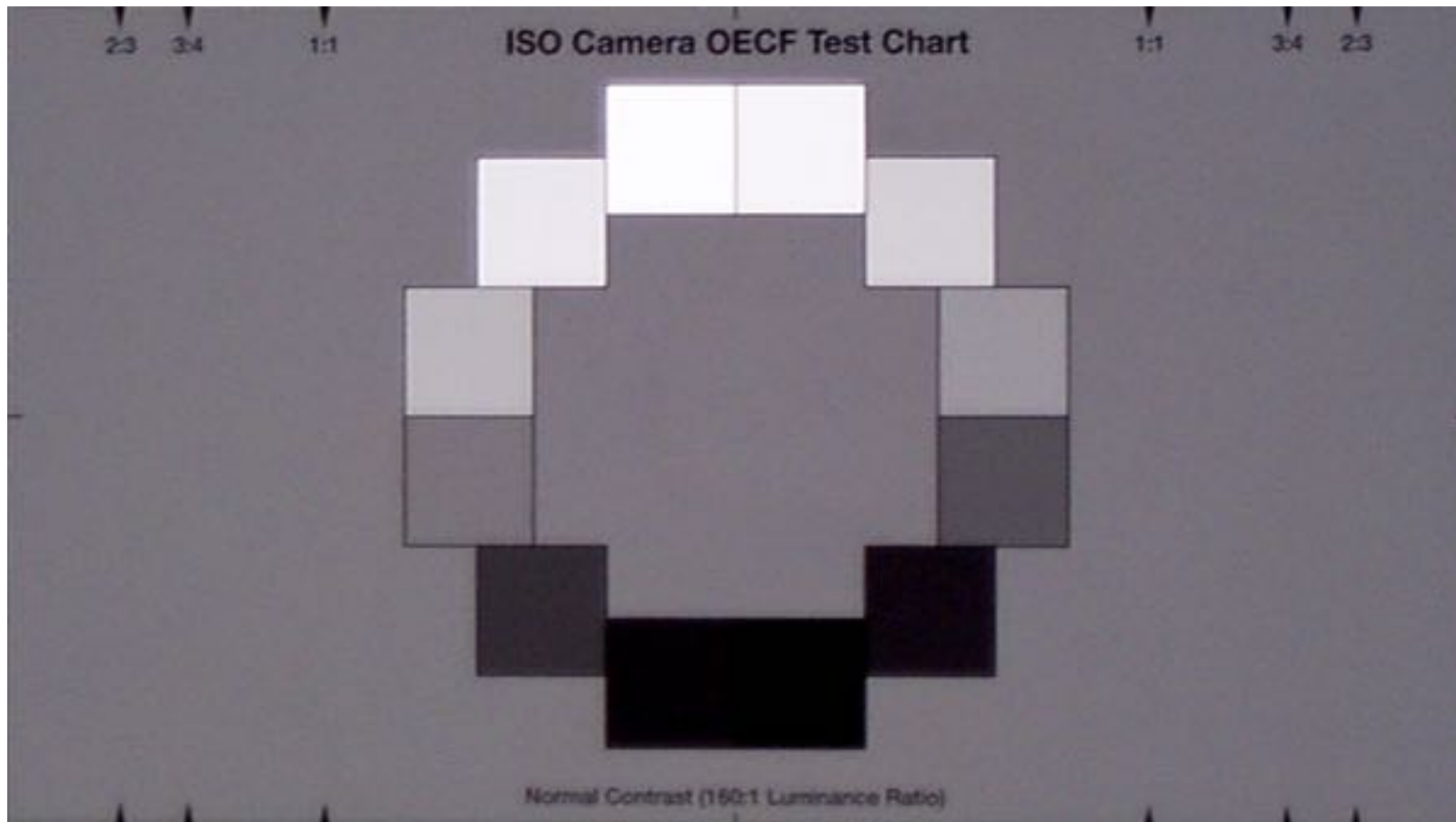
# Objektive Tests

# 2015



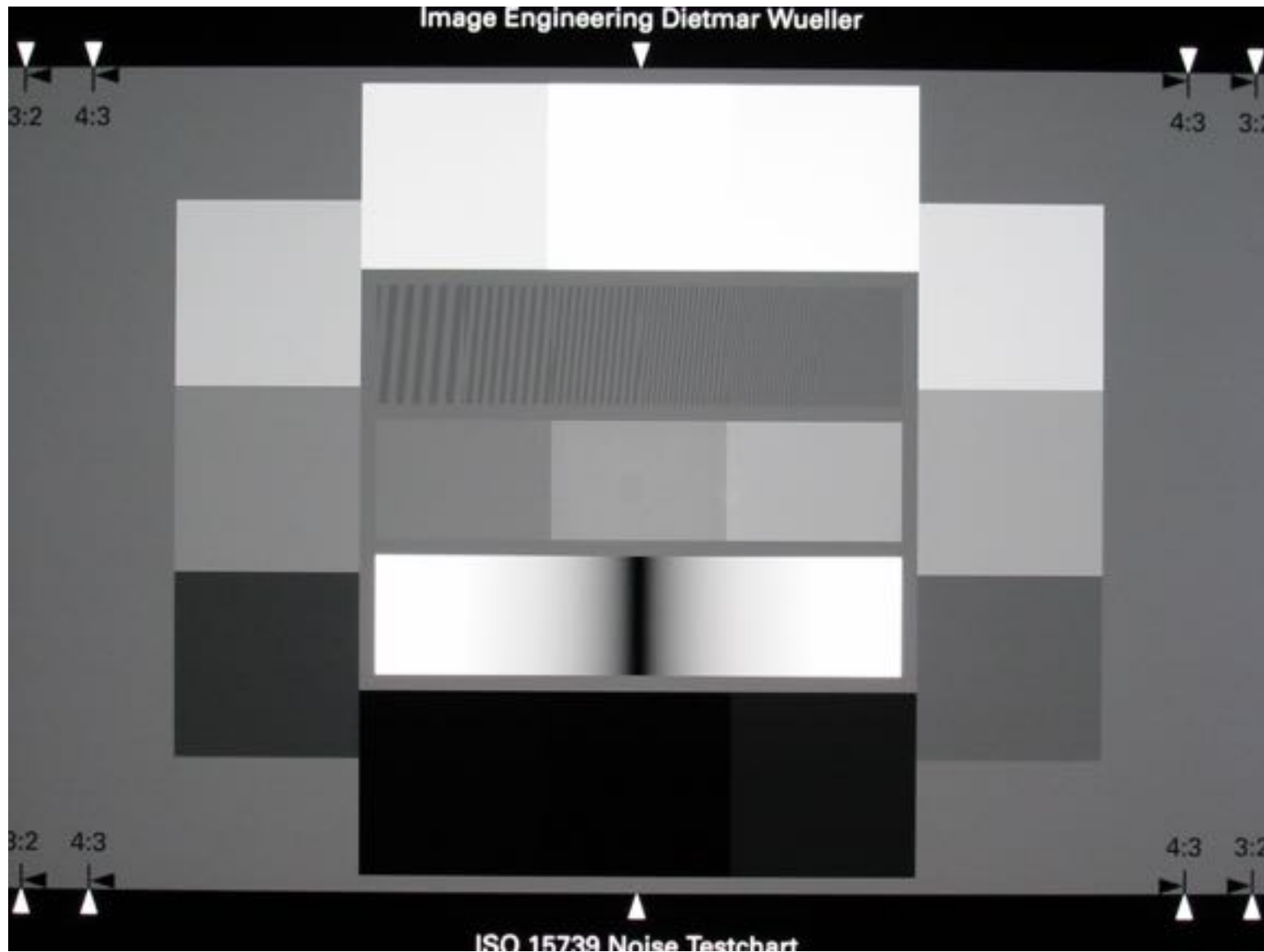
Vollautomatisierter Teststand im Kundenauftrag





Kontrast 160:1 – ab 1997

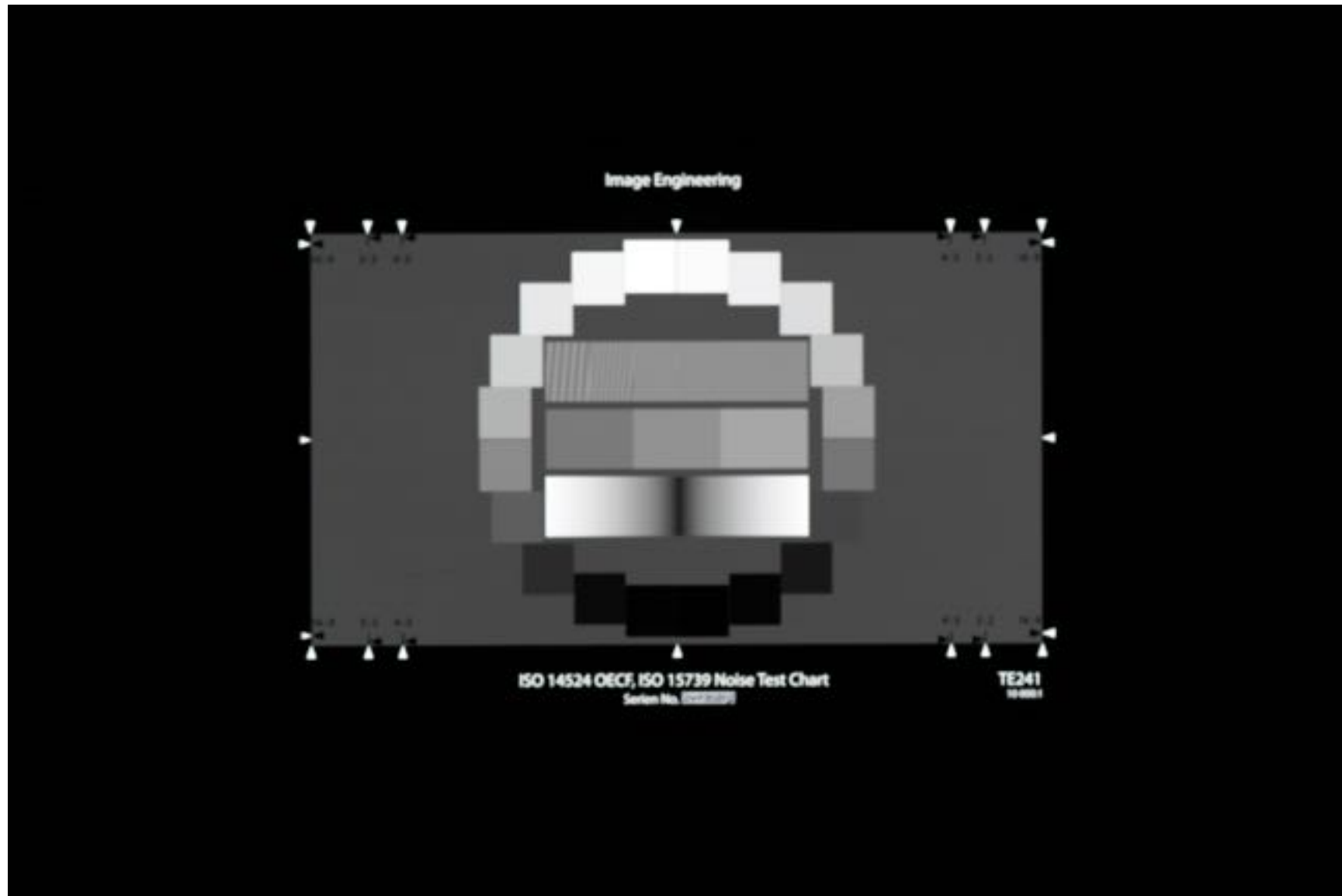




Kontrast 1000:1 – ab 2000

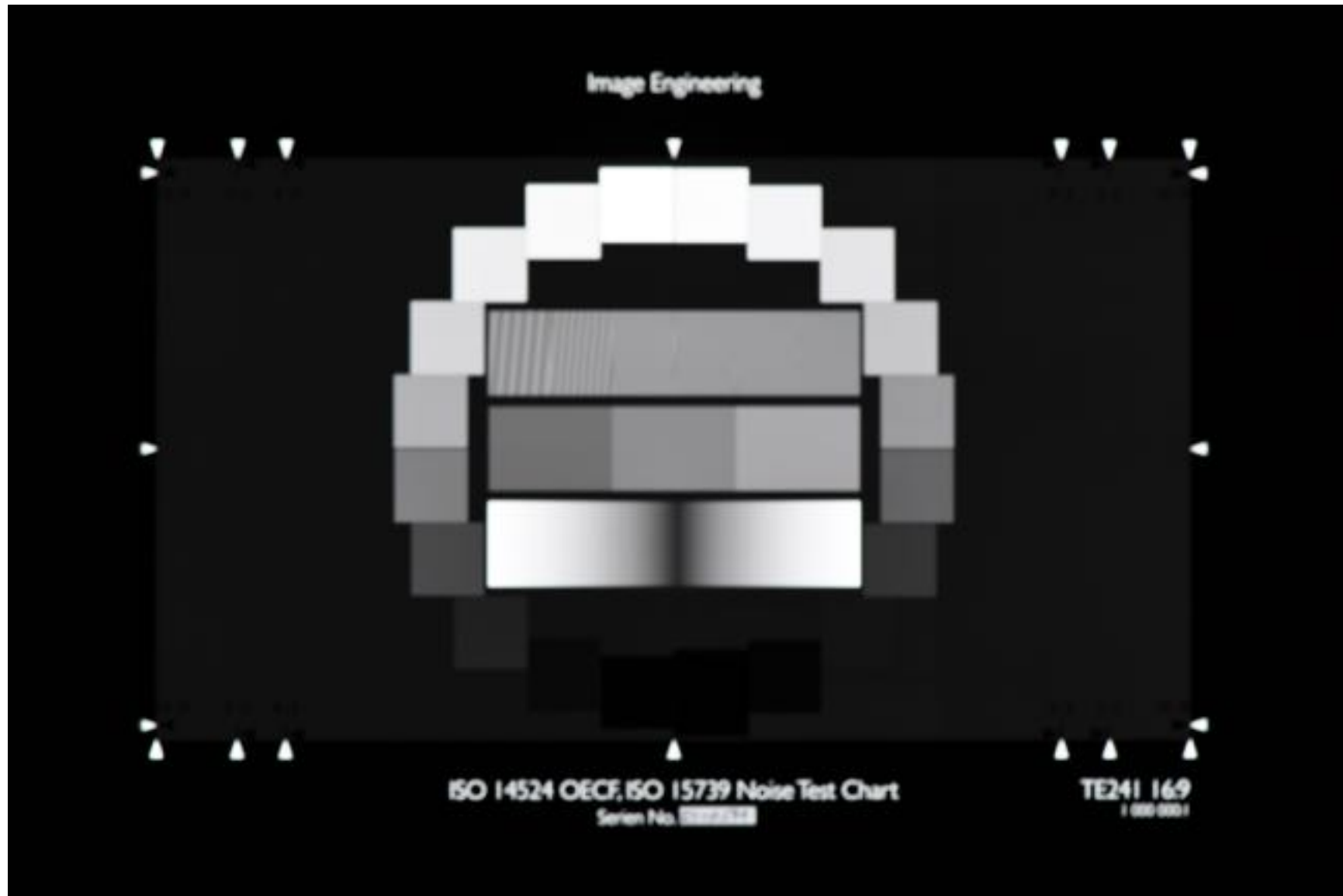






Kontrast 10.000:1 – ab 2003





Kontrast 1.000.000:1 – ab 2015



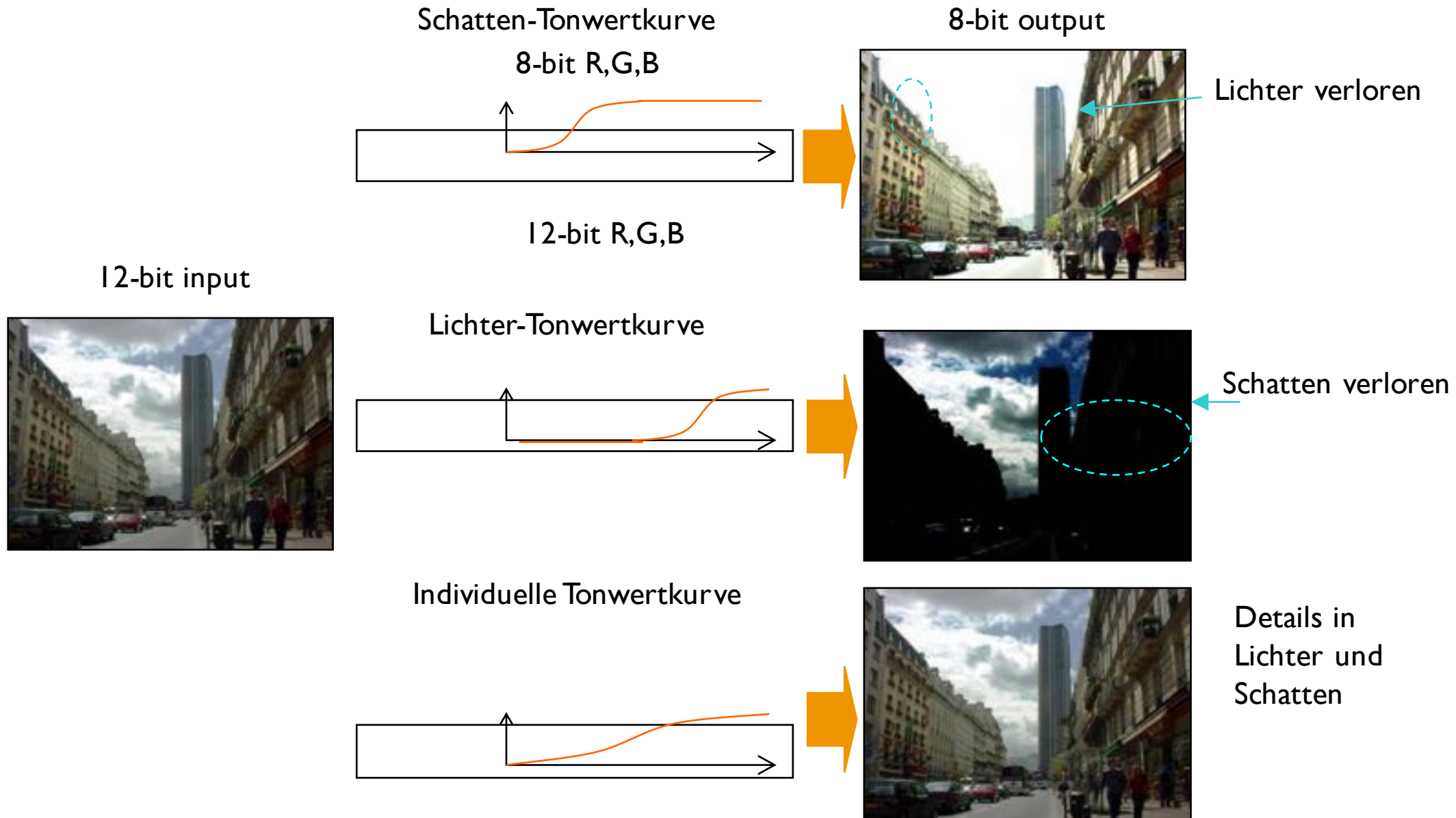


# Dynamic Range





# Rendering







HDR







HDR





# Objektive Tests

## 2004



Auflösungsmessung mit harmonischen Siemenssternen.

- 2,1 m hohes Chart
- max. 20 Megapixel

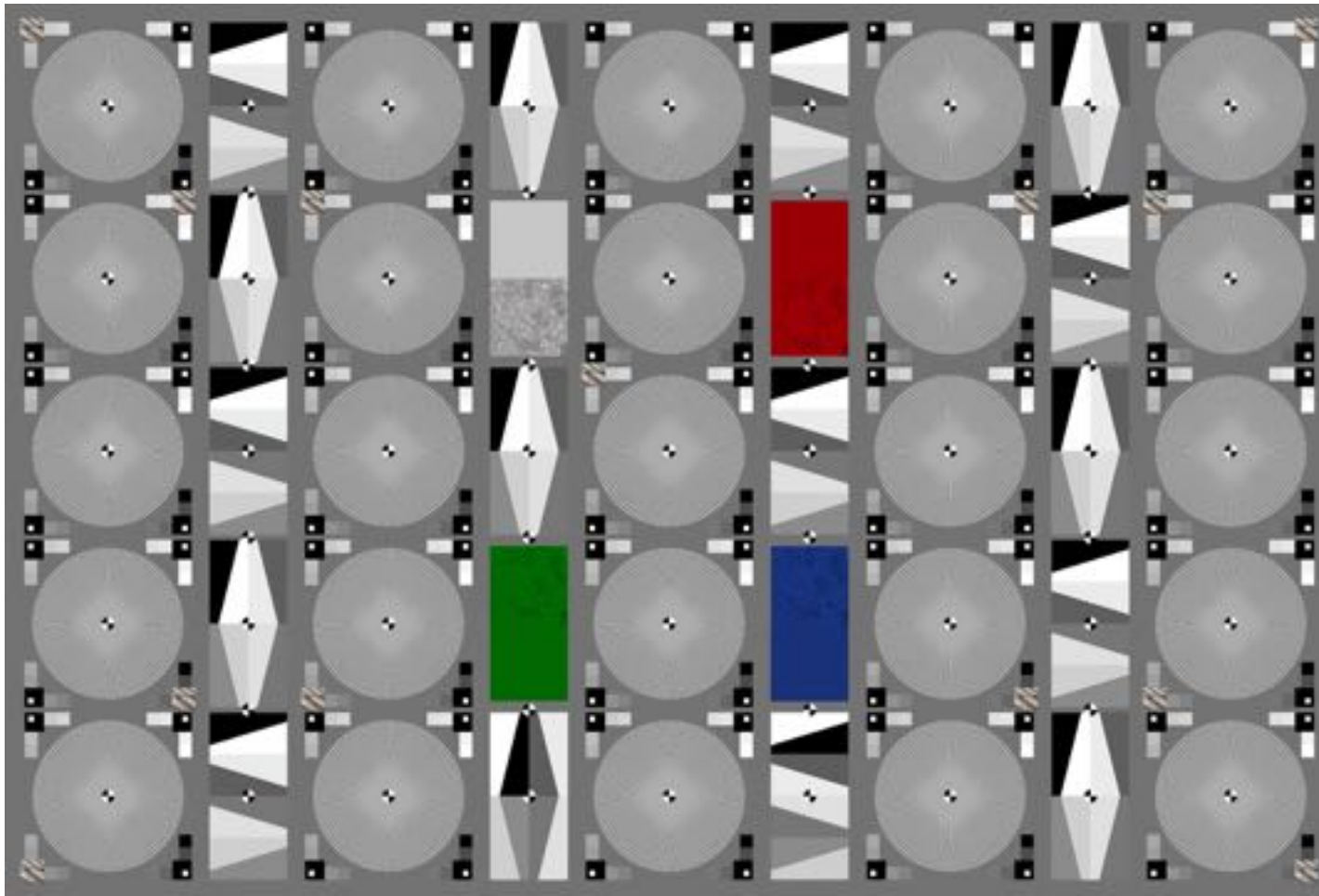
“Image Engineering Diemtar Wüller”  
Komplett digitaler Objektivtest





# Objektive Tests

## 2006



Auflösungsmessung mit  
harmonischen  
Siemenssternen.

- 0,8m hohes Chart
- max. 30 Megapixel

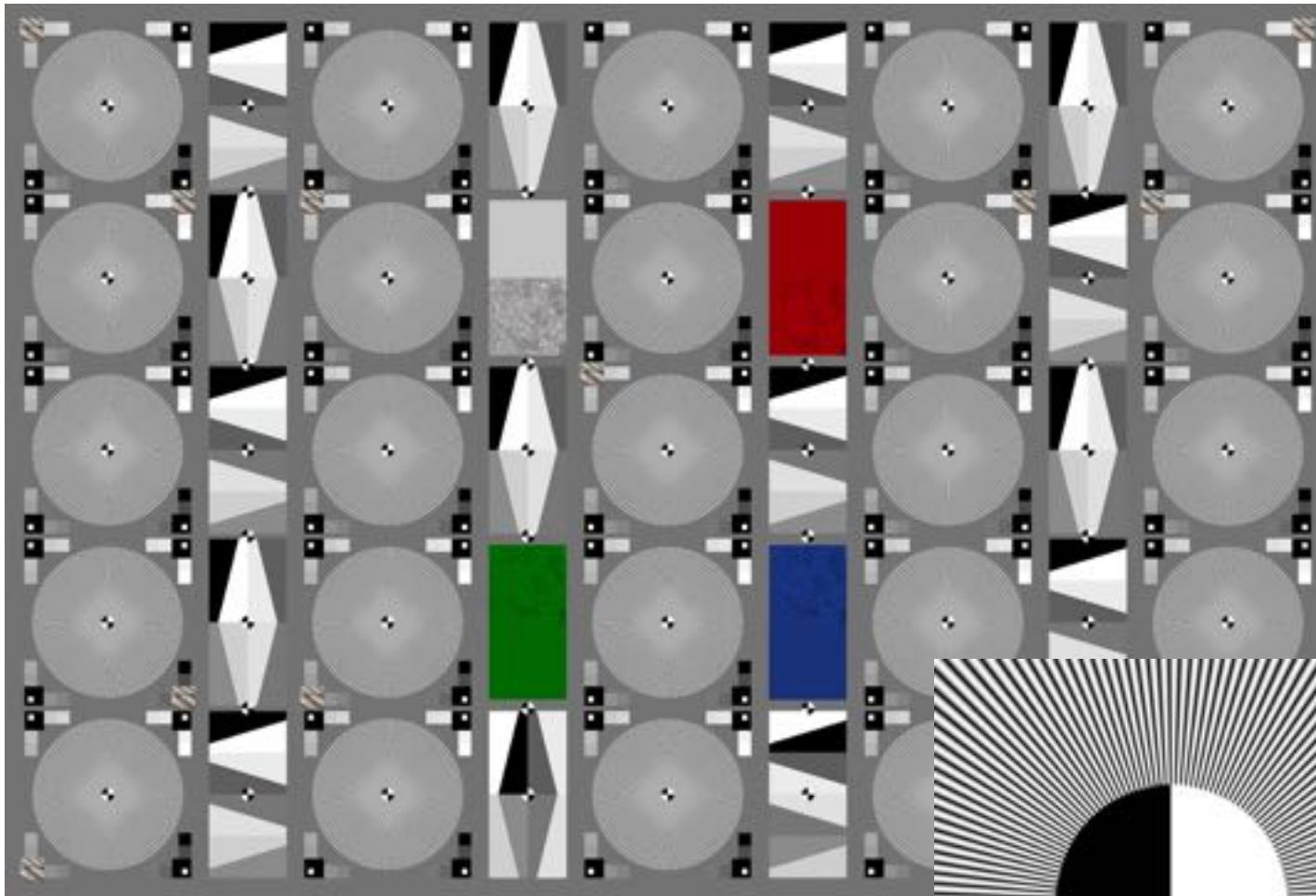






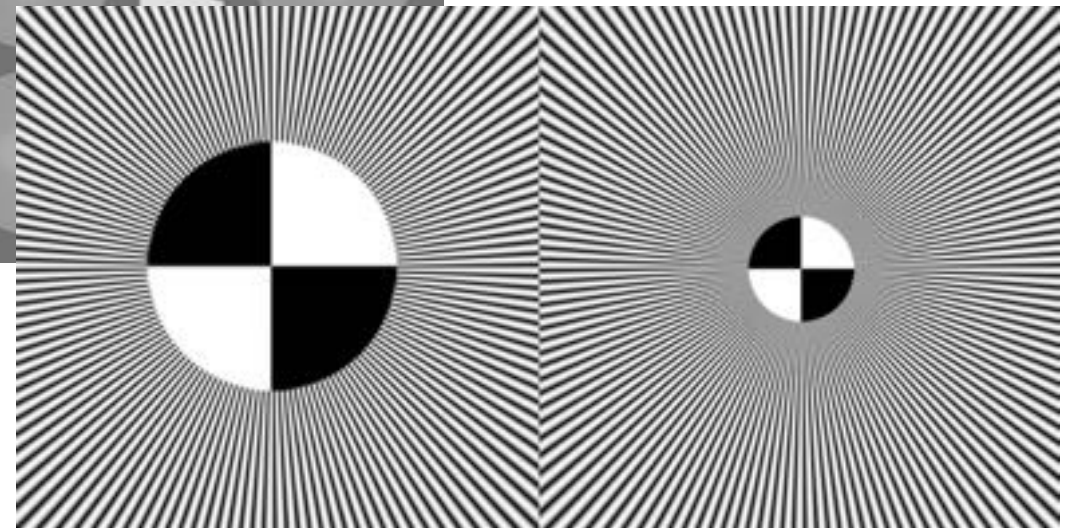
# Objektive Tests

## 2013



Auflösungsmessung mit harmonischen Siemenssternen.

- 0,8m hohes Chart
- max. 180 Megapixel



12mm → 5mm

[www.image-engineering.de](http://www.image-engineering.de)





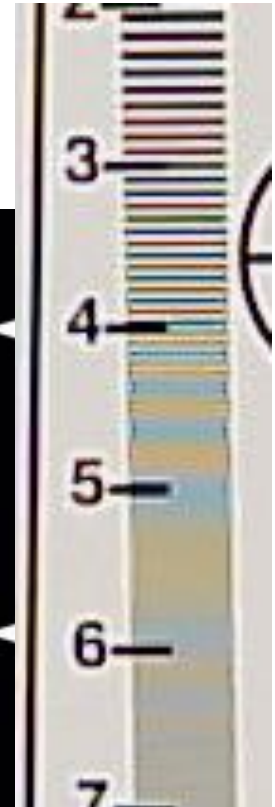
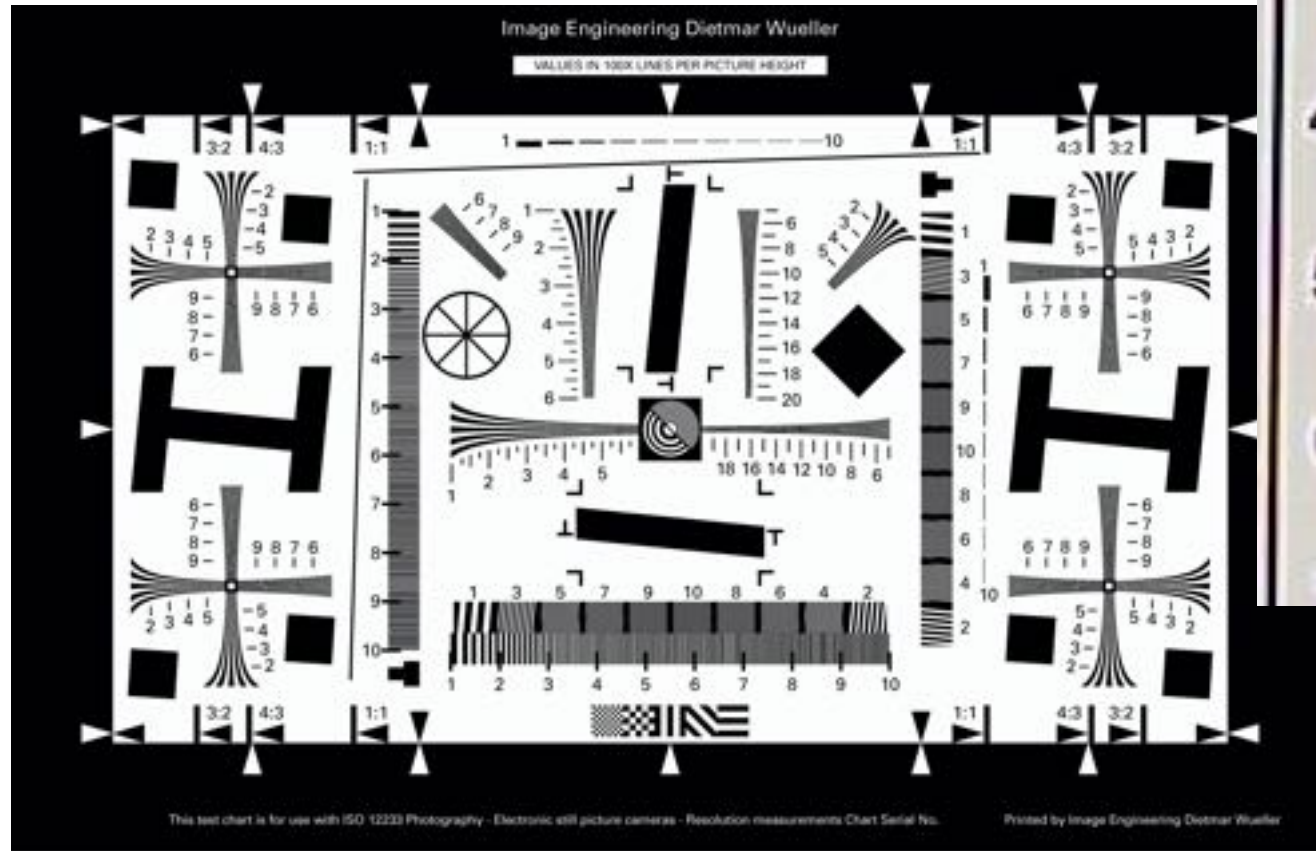
- Kameras werden besser – Messverfahren müssen mithalten
- **Neue Technologien erfordern neue Messverfahren**
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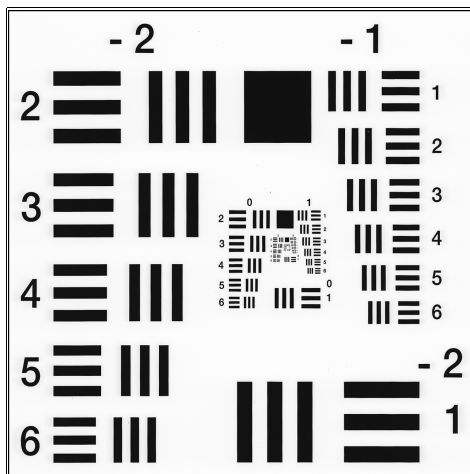




# ISO12233 – 2000 // Visuelle Auswertung oder Kante



USAF Chart



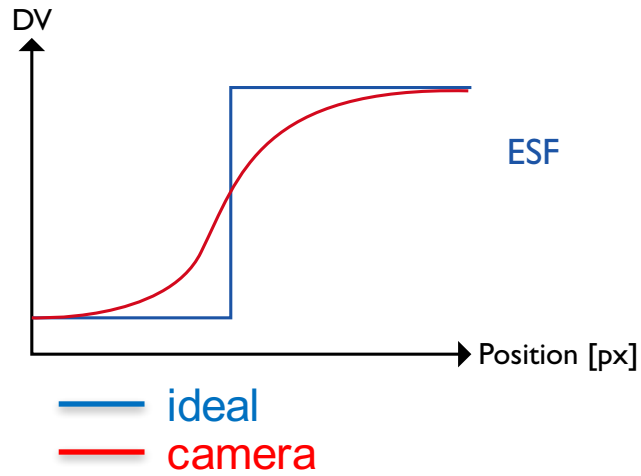
ISO 12233-2000



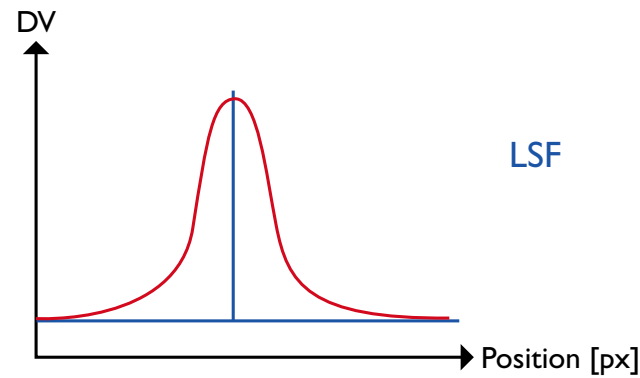


# Resolution – Slanted edge

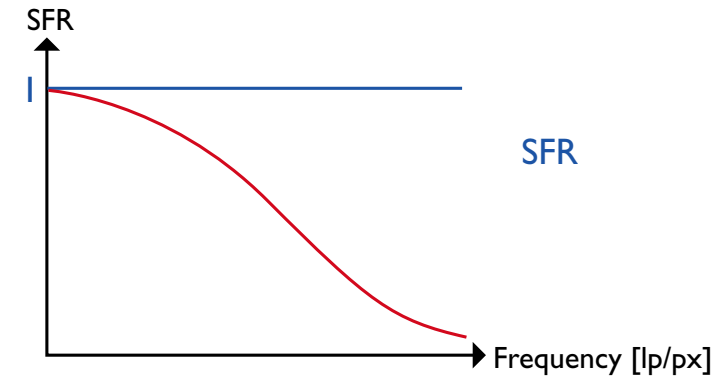
Edge Spread Function  
 $f(x)$



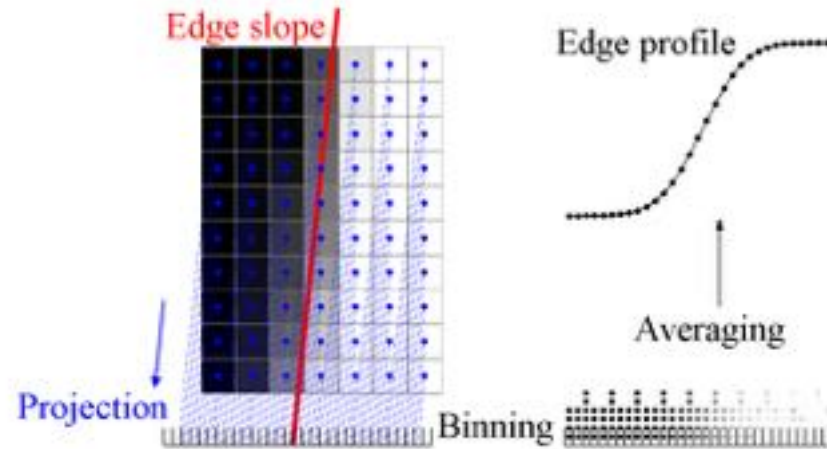
Line Spread Function  
 $f'(x)$



SFR  
Fourier( $f'(x)$ )



(a)

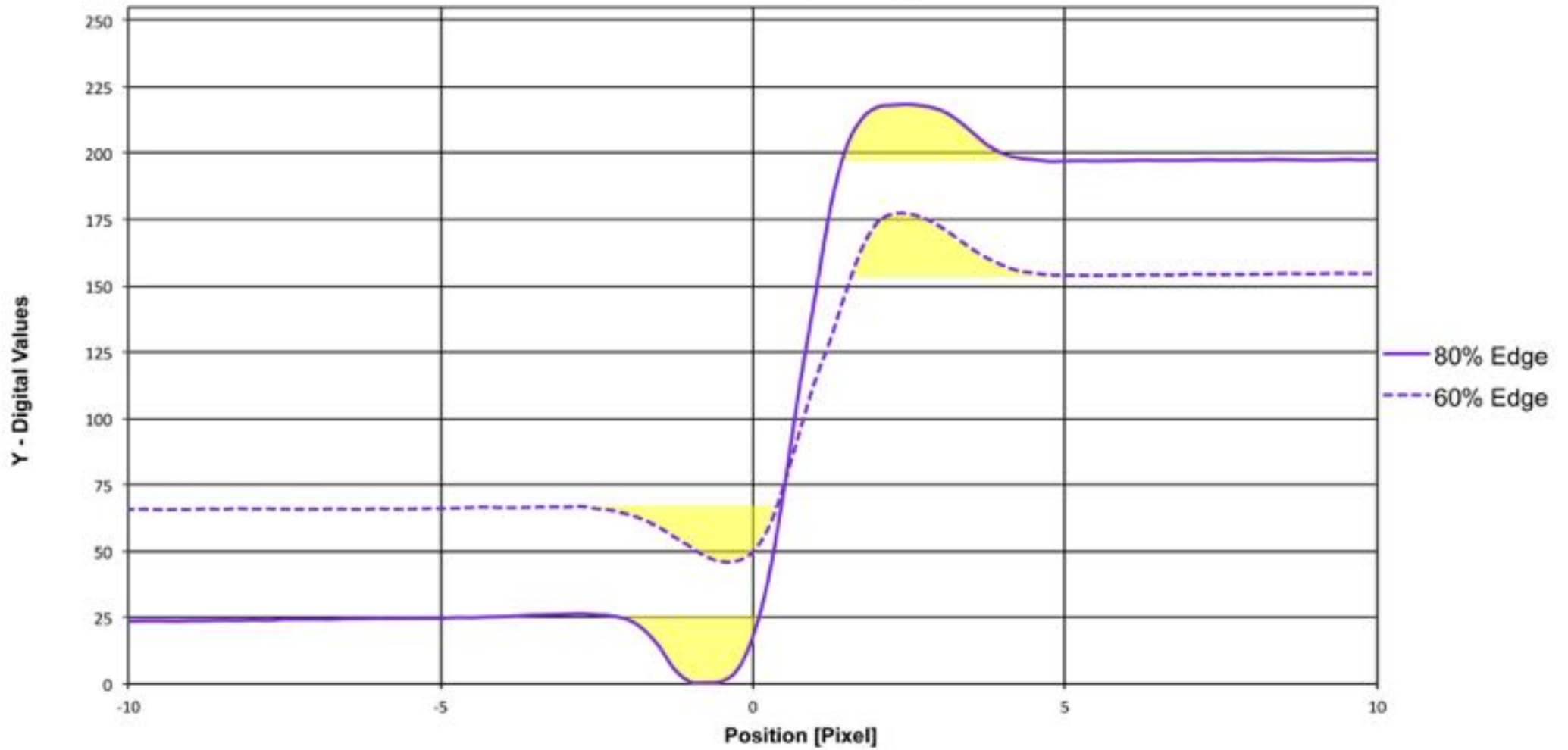


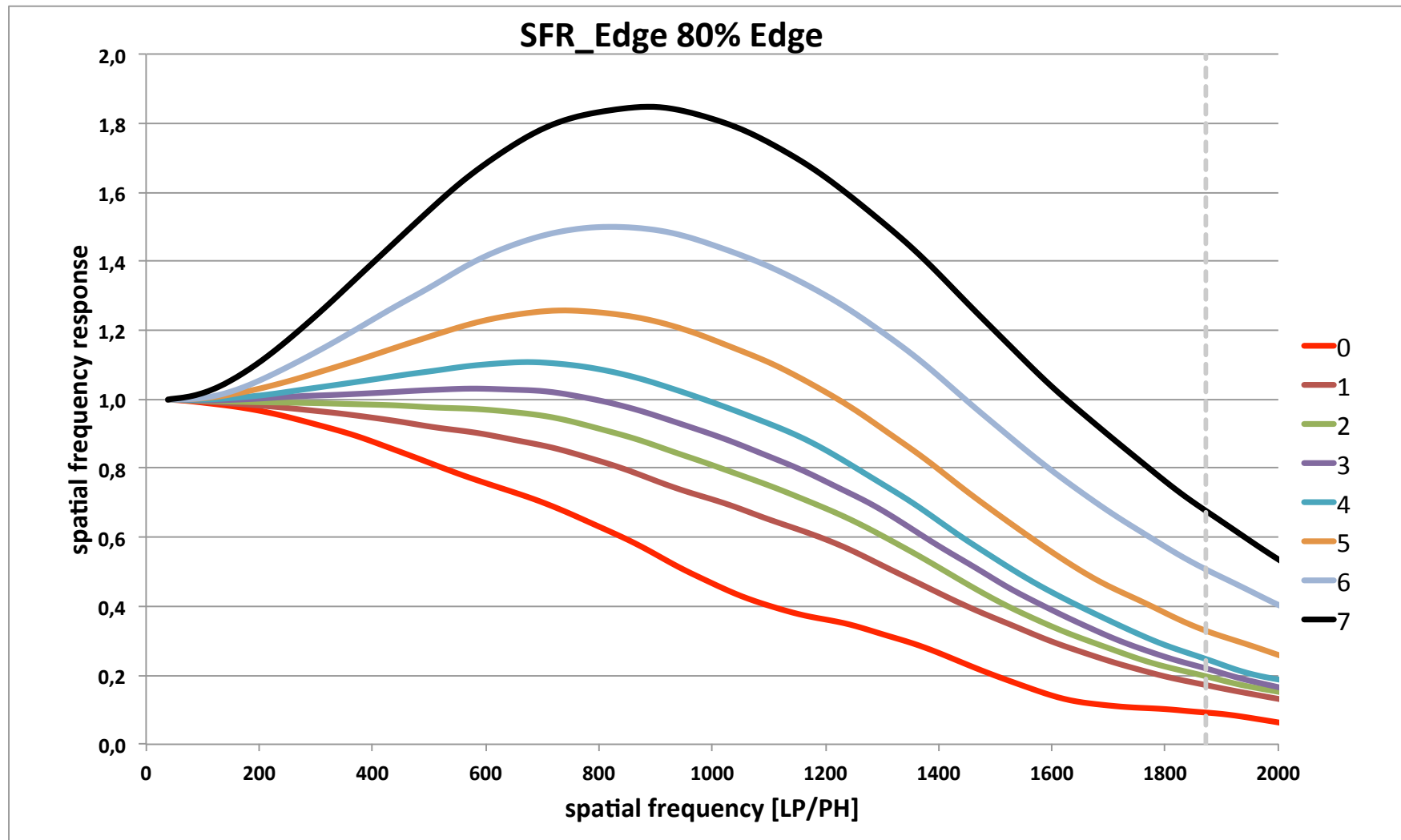
(b)





## ESF - Sharpening



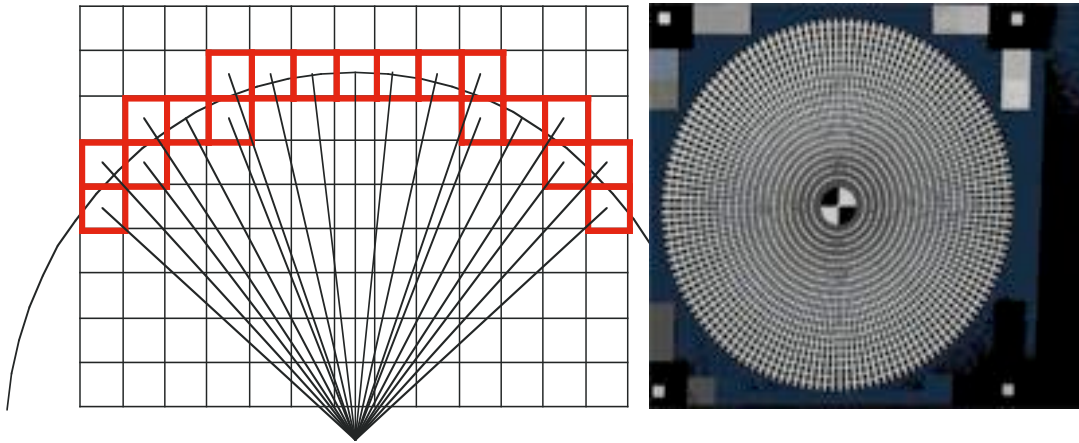


Die Analyse der schrägen Kante ist stark durch Bildoptimierung wie z.B. Schärfung beeinflusst.

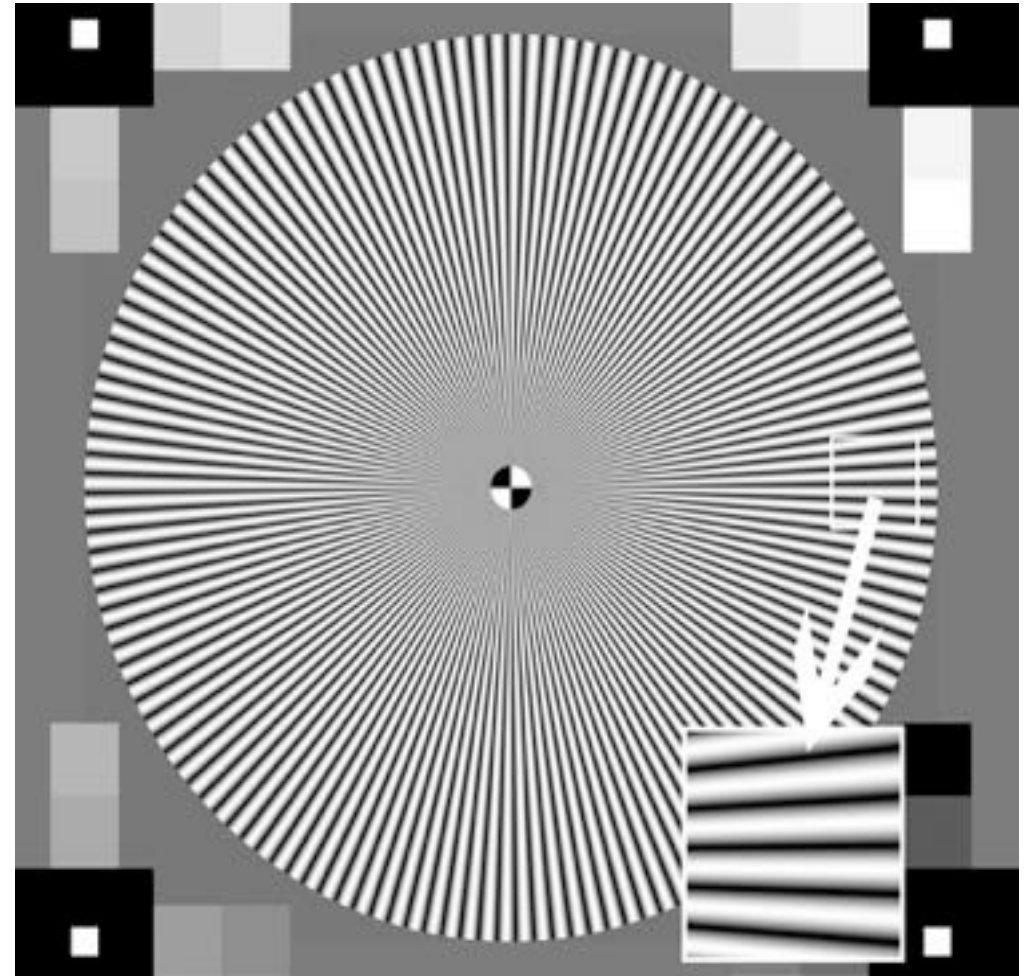
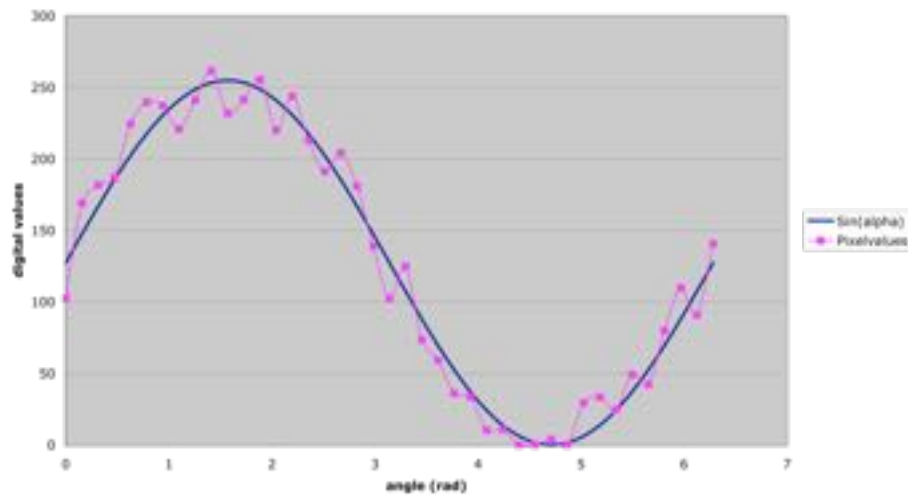




# Auflösungsmessung



Sine function fitted into the digital values

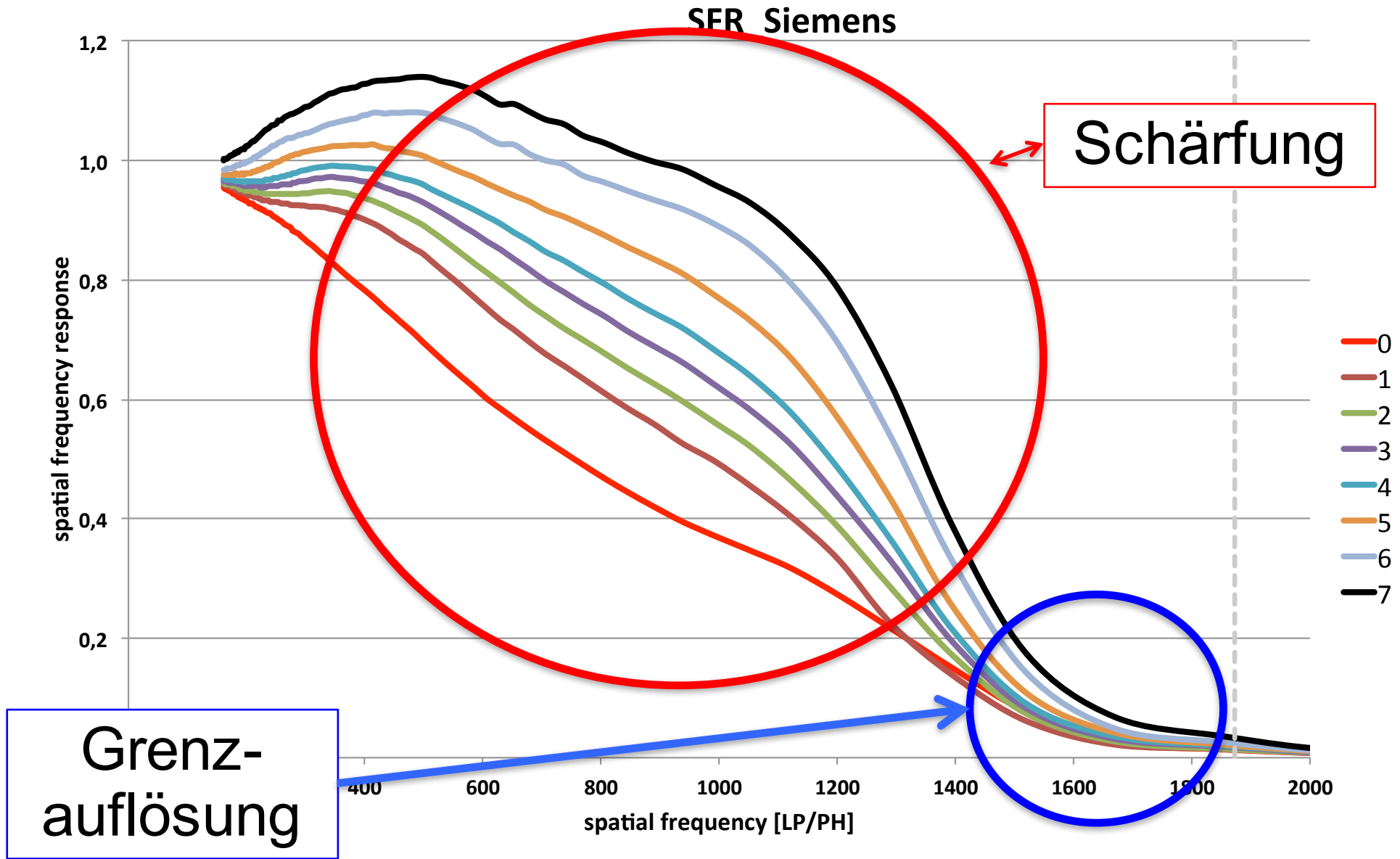


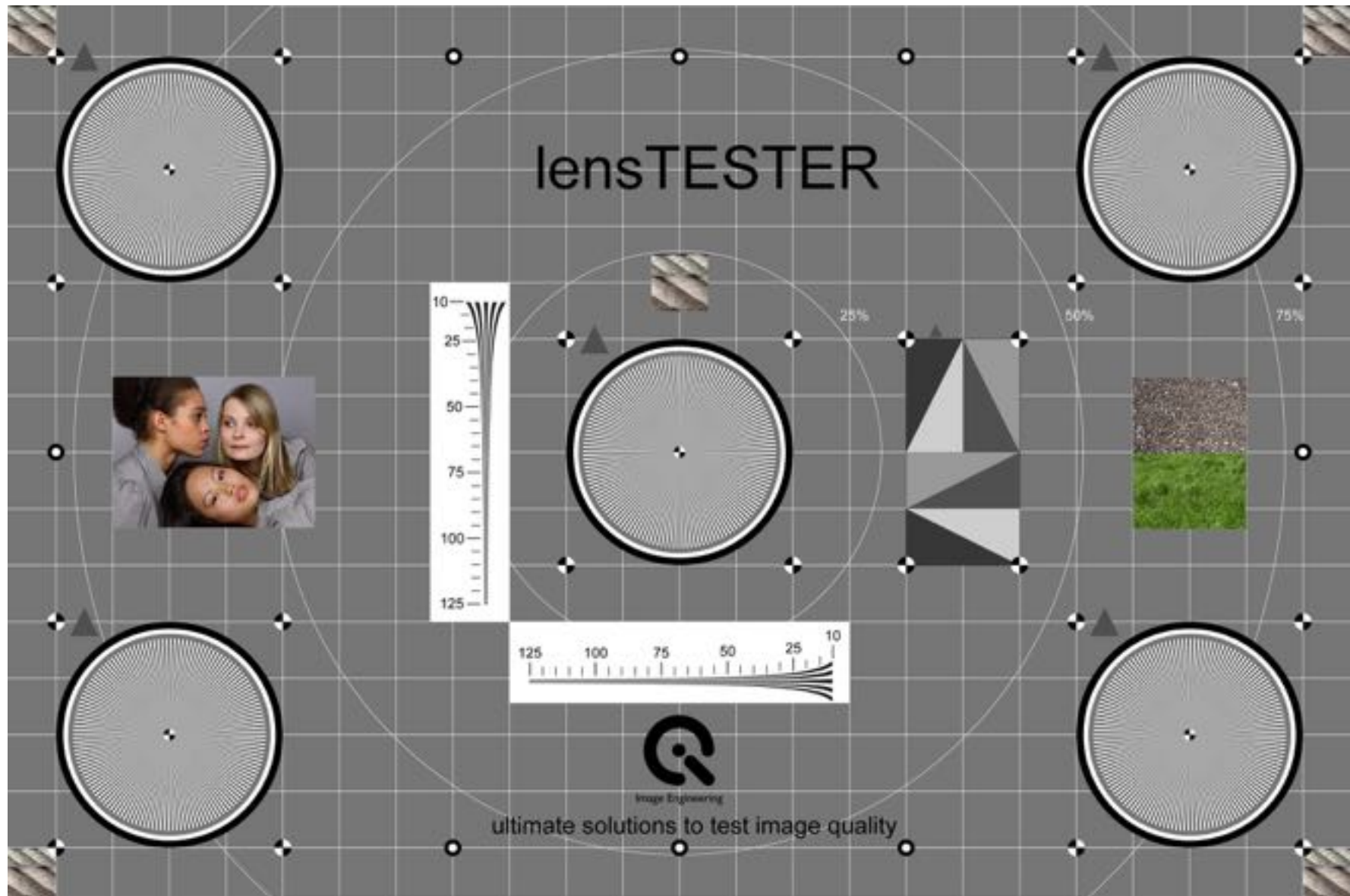
ISO12233-2014

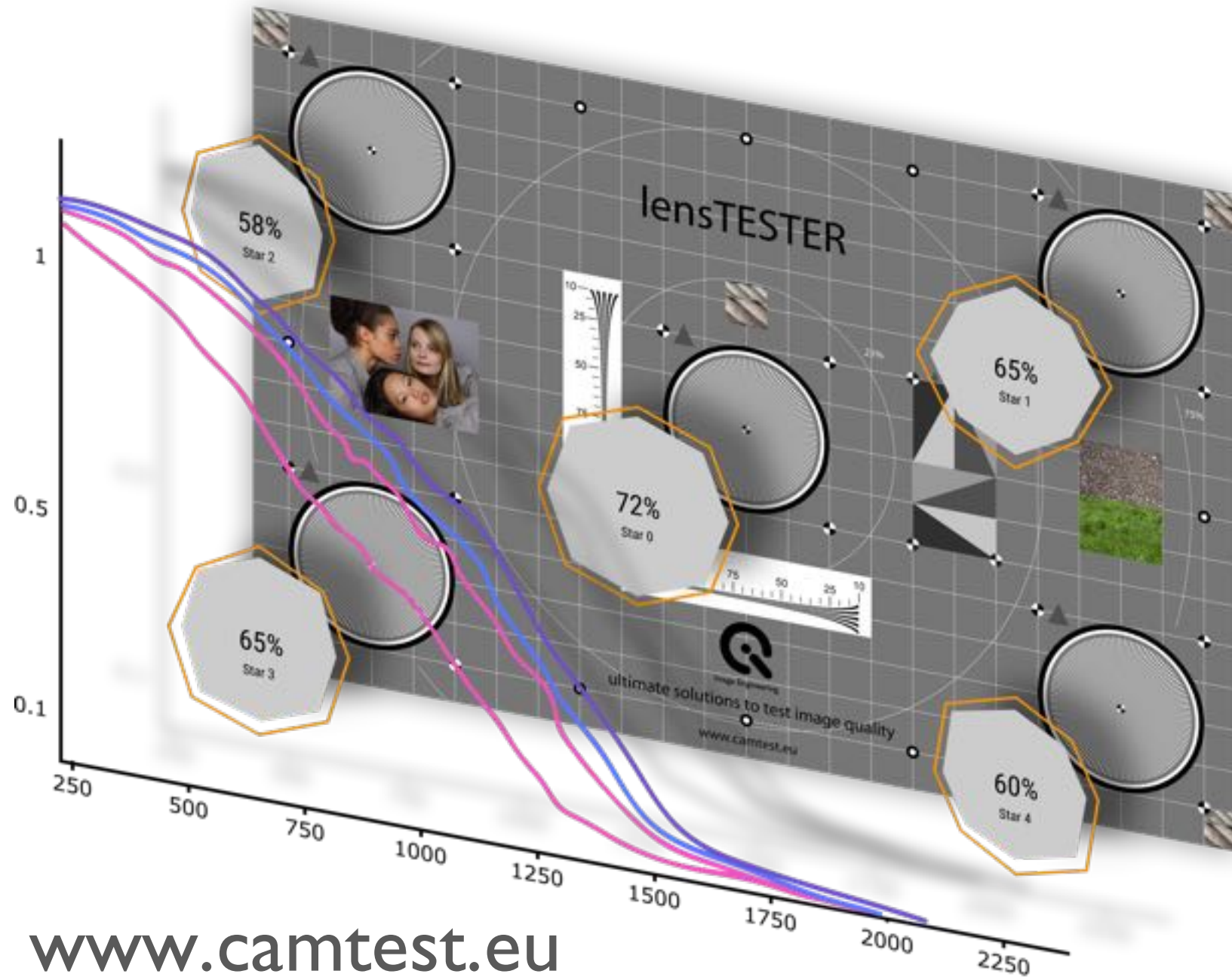
Entwickelt durch Image Engineering 2003











[www.camtest.eu](http://www.camtest.eu)



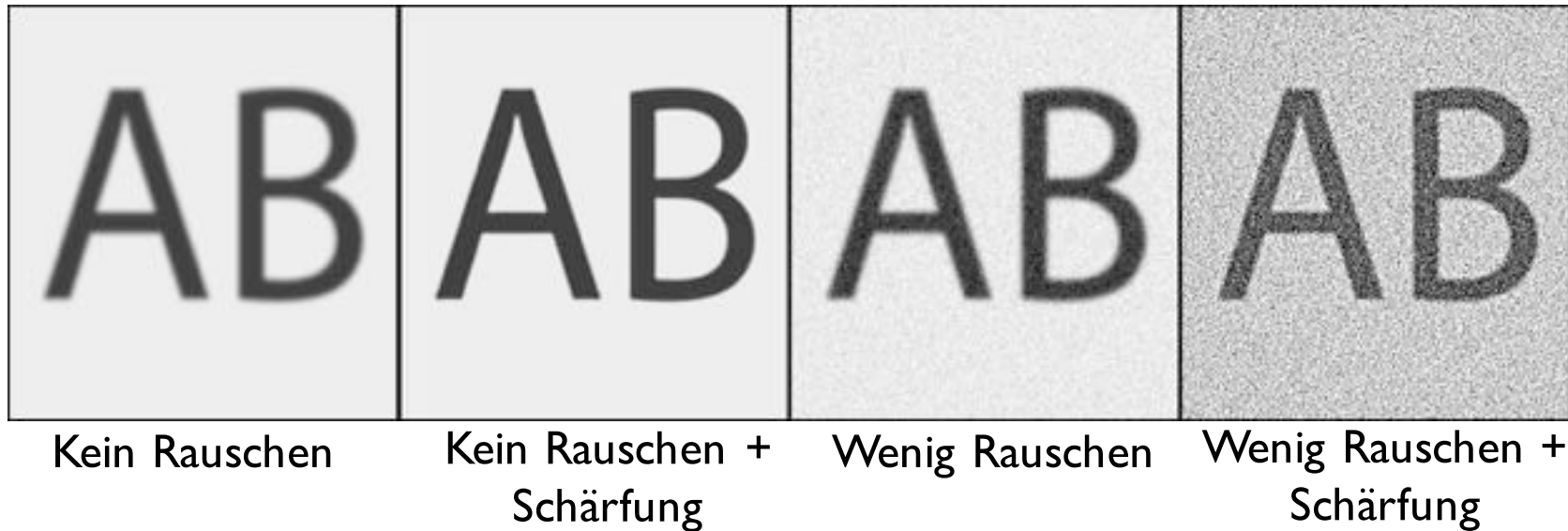


www.camtest.eu





## Sharpness vs. Noise vs. Texture loss







# Texture loss

Tuning

Sharpness

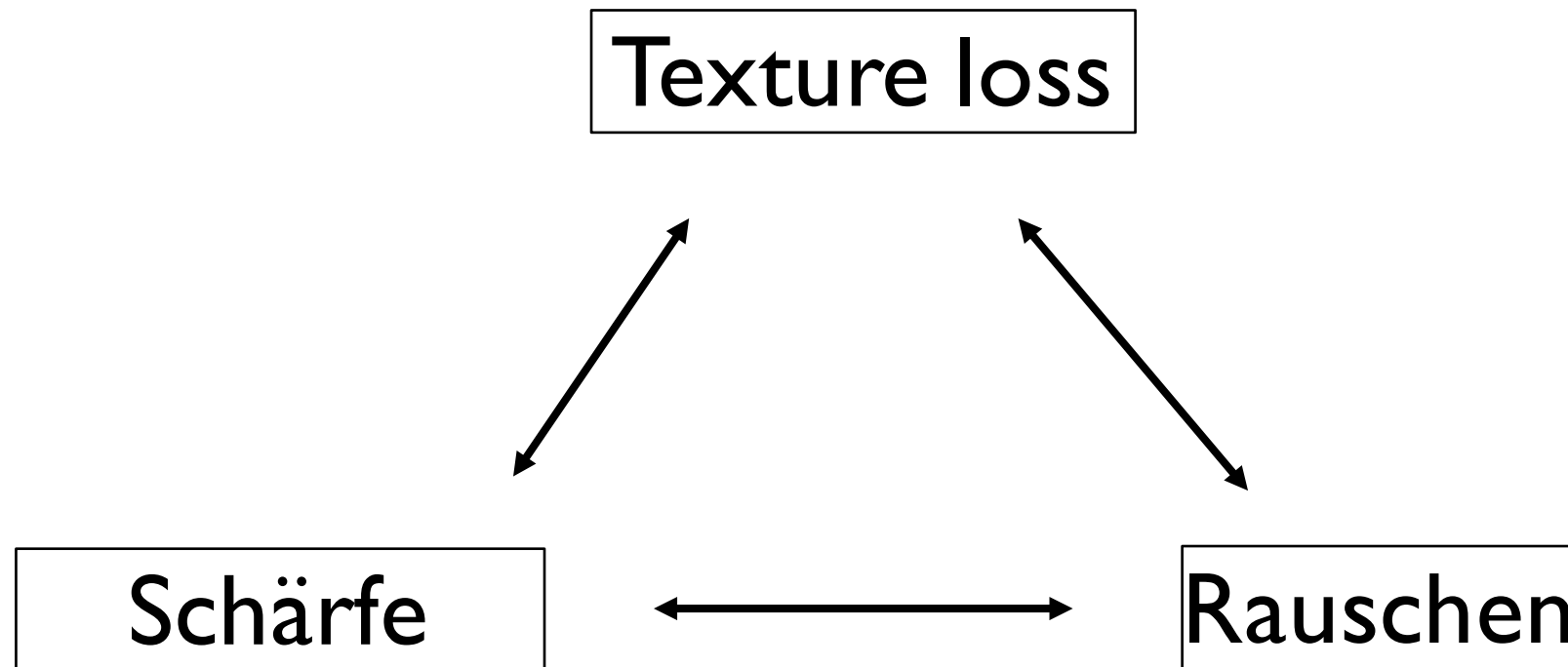


Noise





Tuning





# Texture loss





# Texture loss





# Texture loss

## Phone I

D50 / 63lux

higher noise  
more details







# Texture loss

**Phone 2**  
D50 / 63lux

low noise  
less details





- Eine Kamera stellt ein komplexes System dar. Es ist wichtig nicht nur einzelne Teile zu beurteilen.

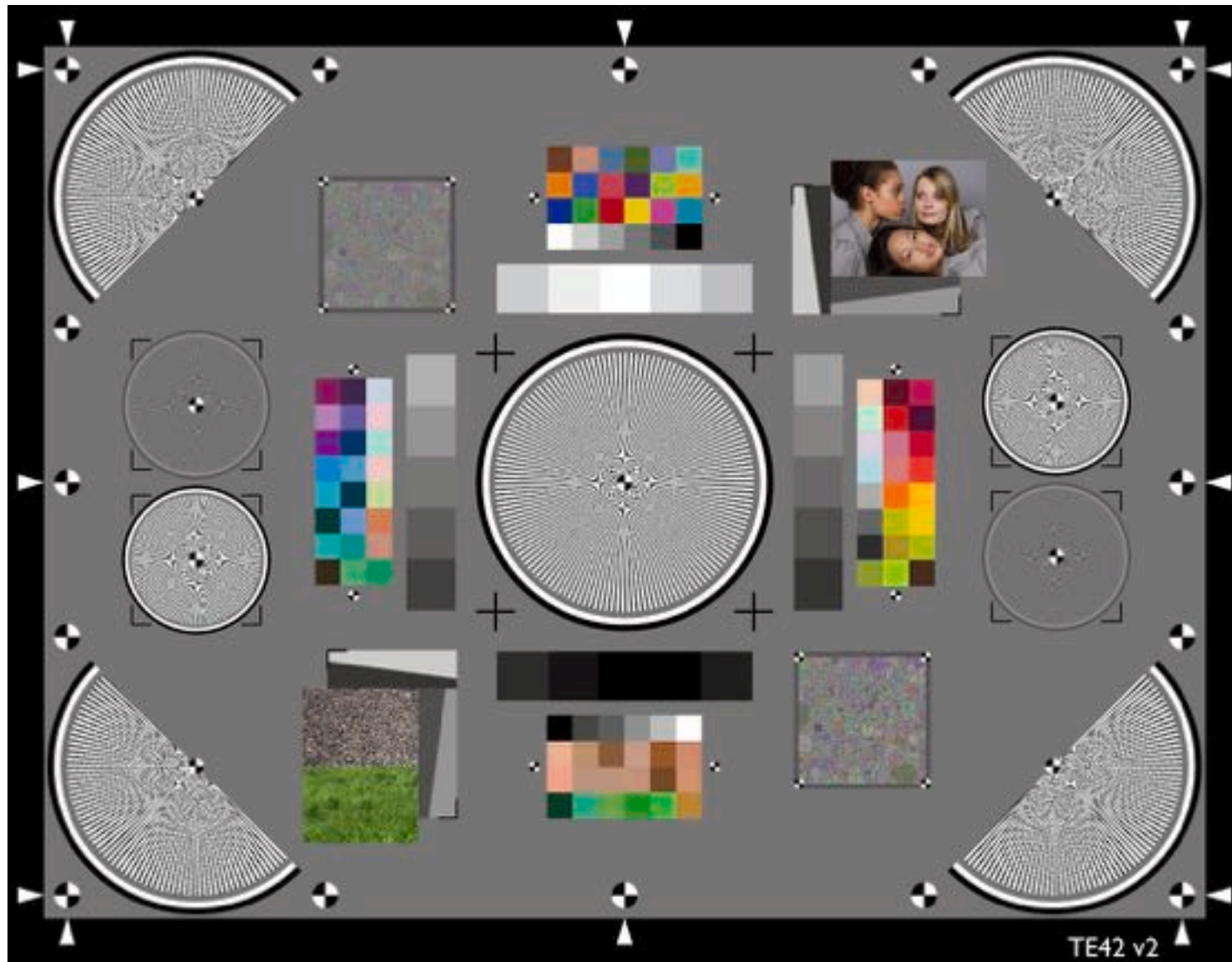


**Kürzester Bremsweg !**



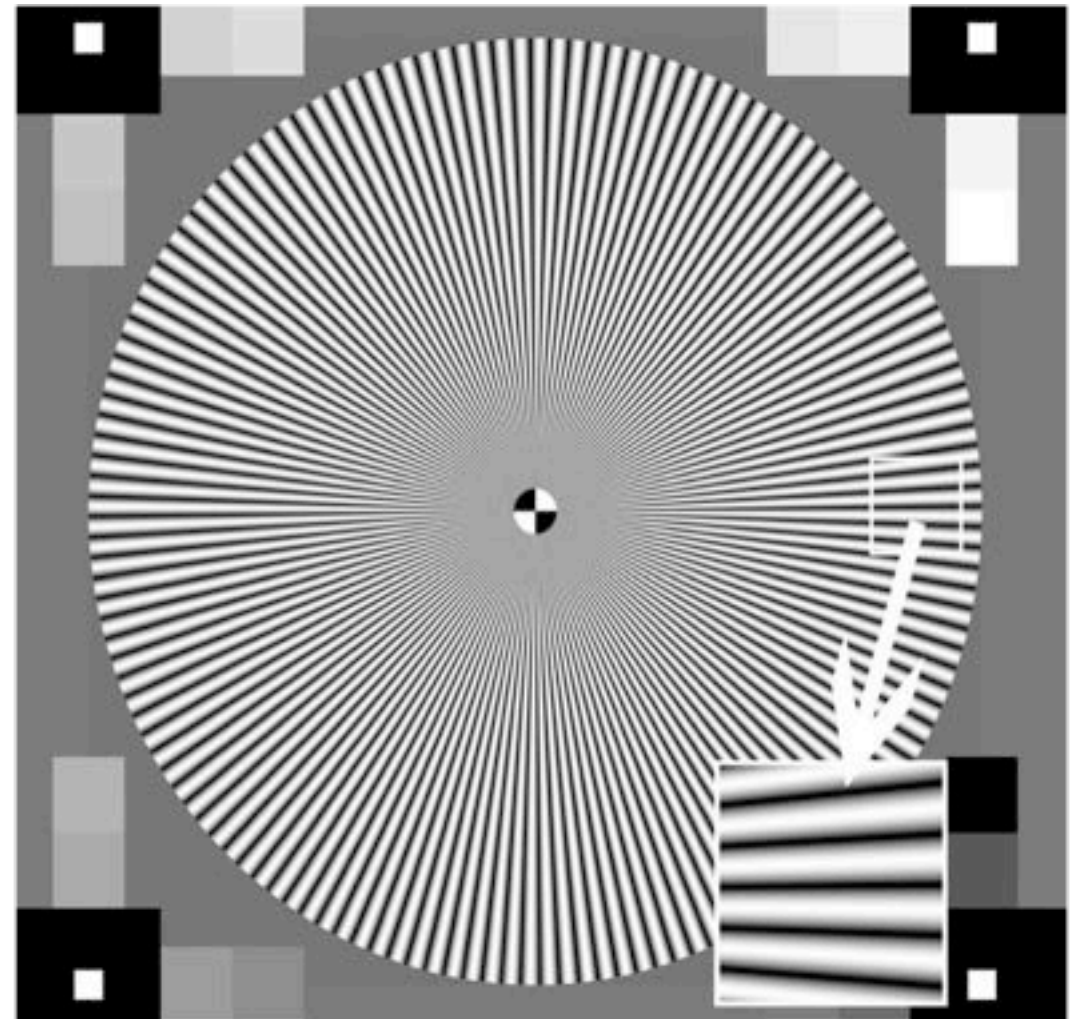
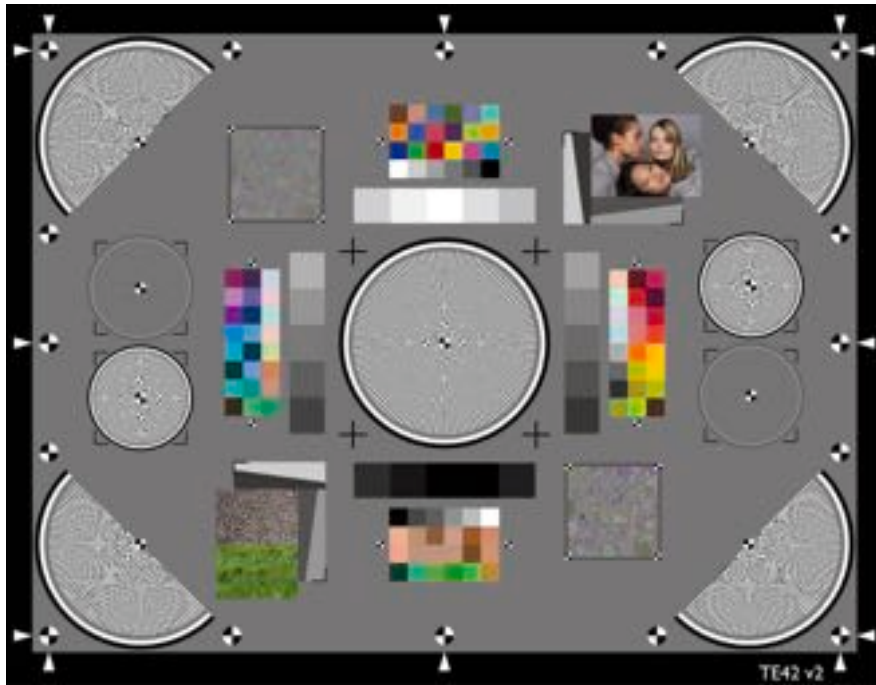


# Spatial Frequency Response





# Spatial Frequency Response



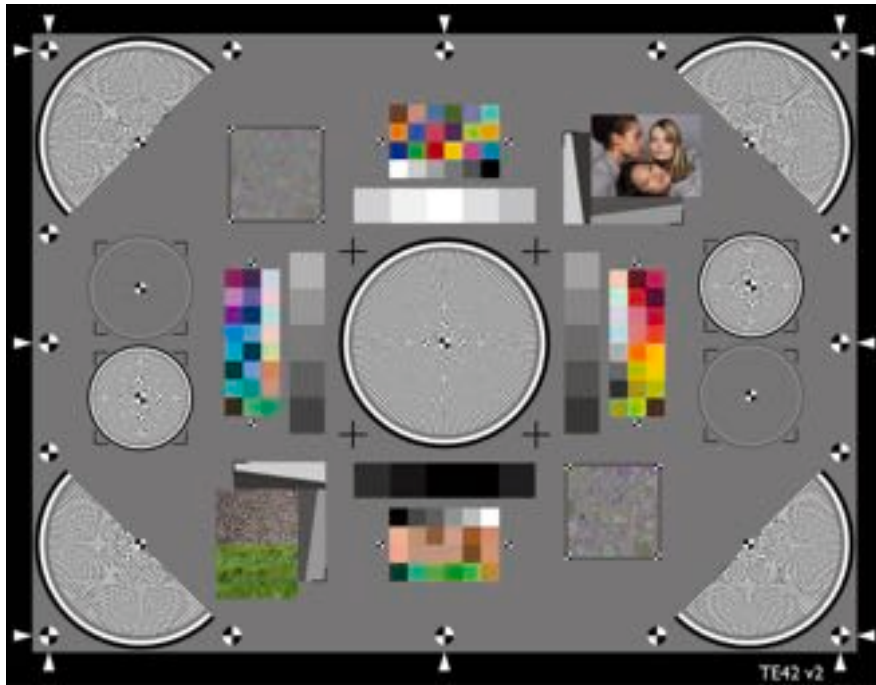
SFR-Siemens based on a sinusoidal Siemens star. It is part of the standard ISO12233:2014  
“Photography - Electronic still picture imaging - Resolution measurements”







# Spatial Frequency Response



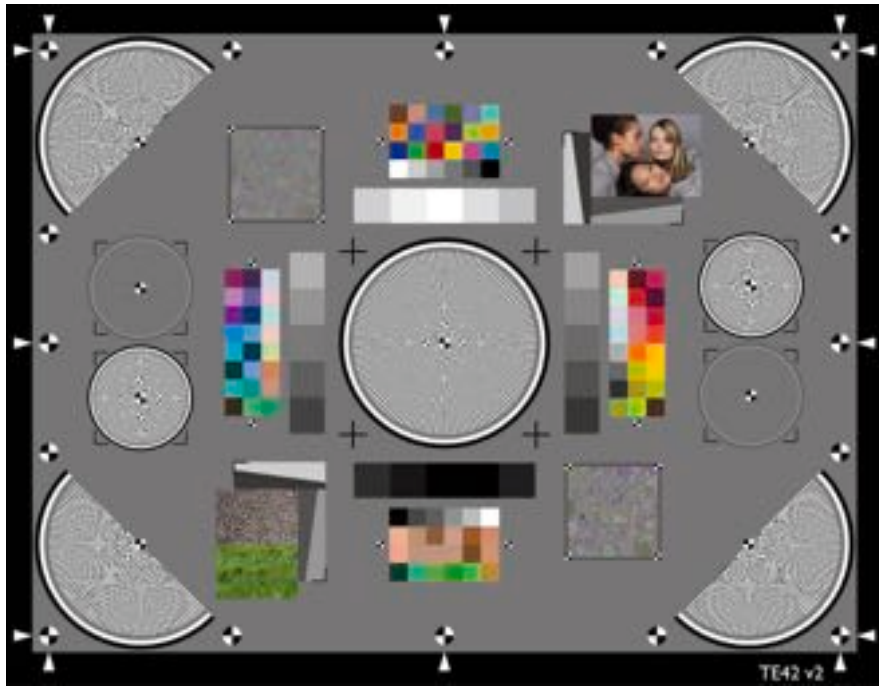
SFR-Edge measured on a 60% edge and a 80% edge. It is part of the standard ISO12233:2014  
“Photography - Electronic still picture imaging - Resolution measurements”



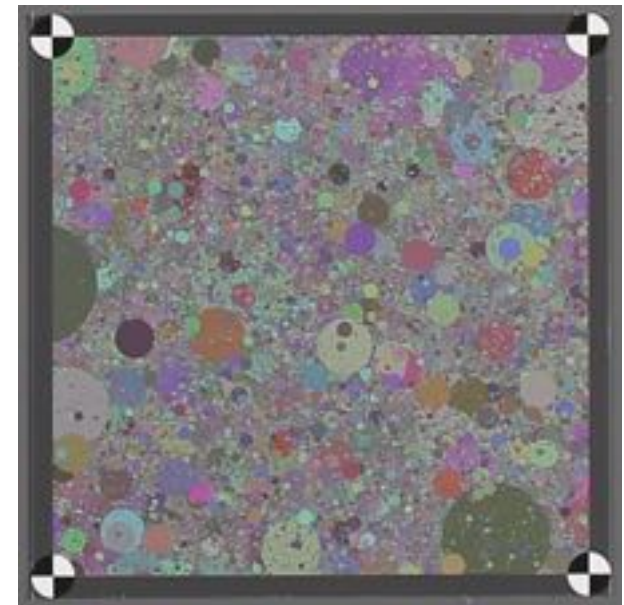
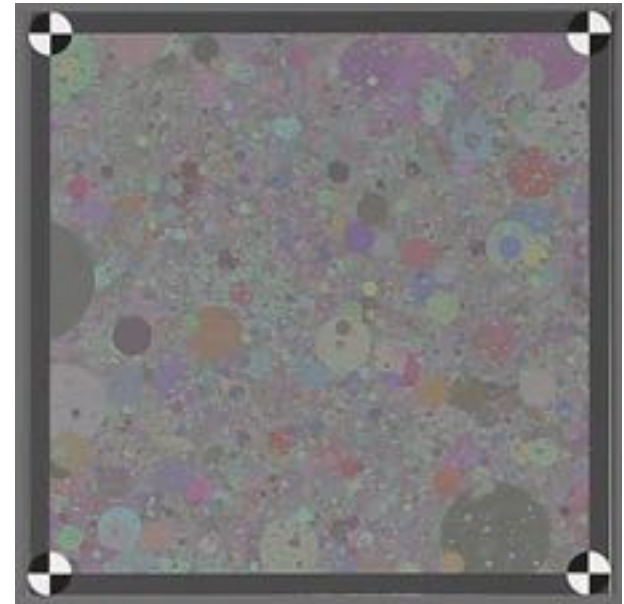


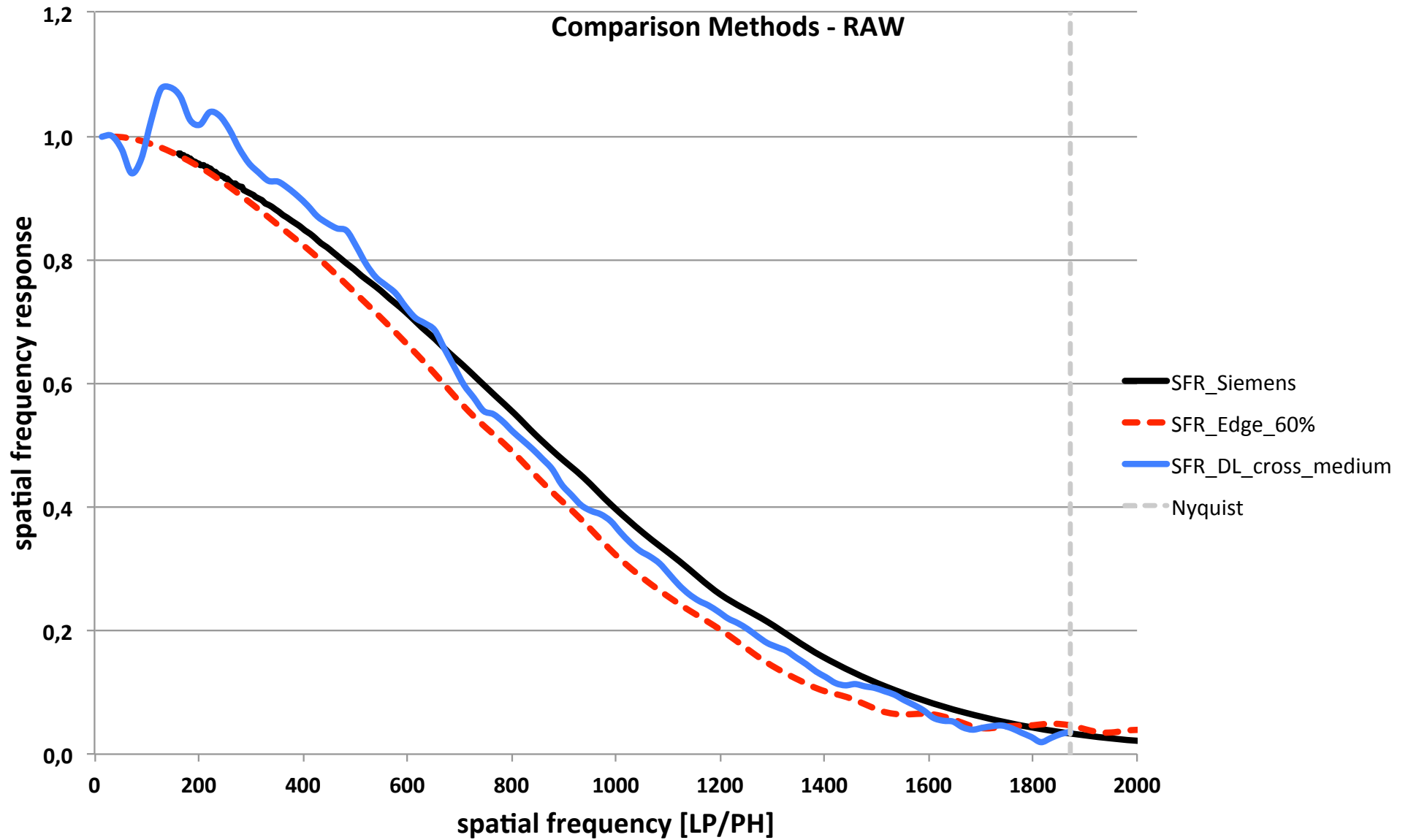


# Spatial Frequency Response



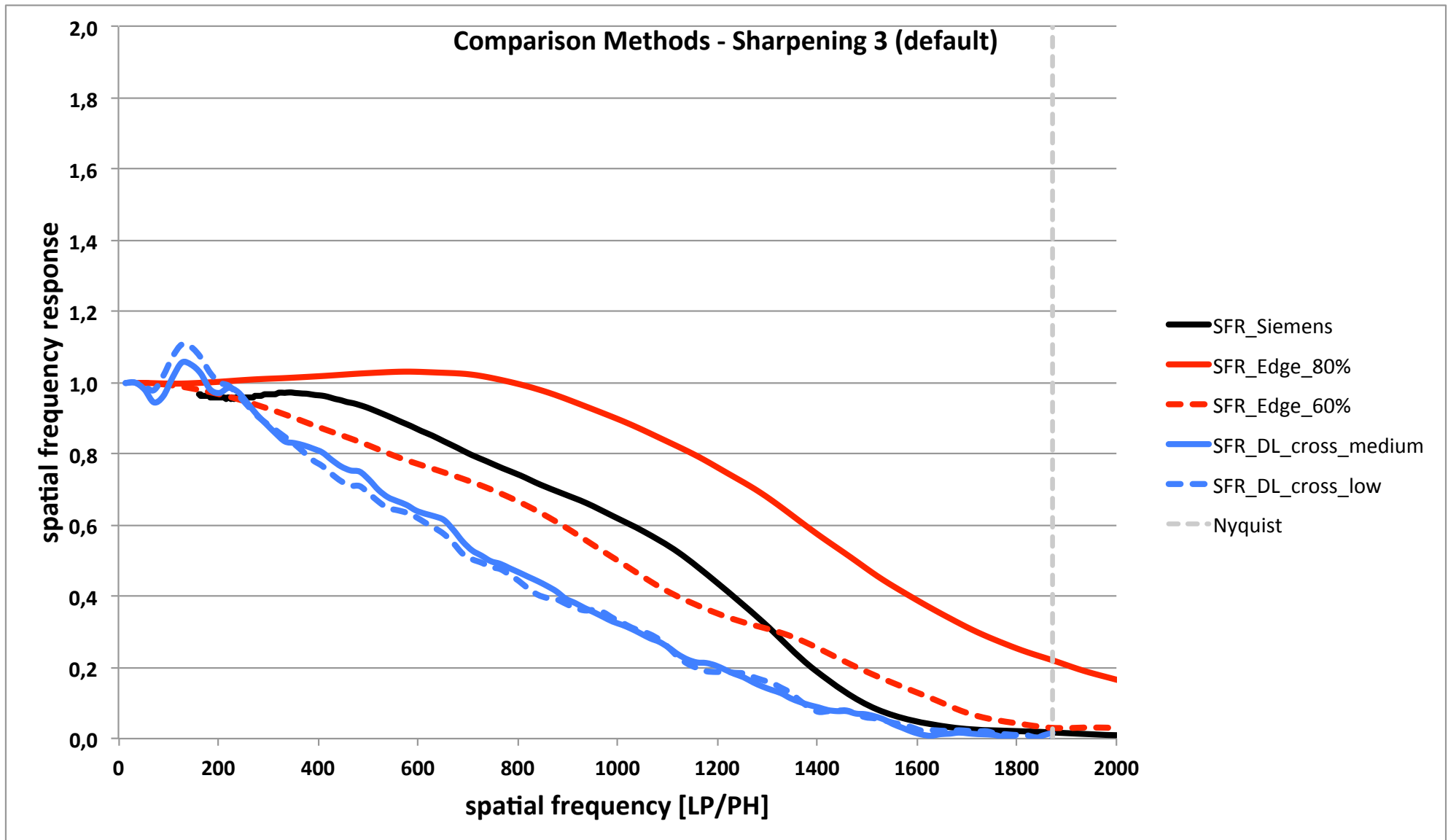
Dead Leaves pattern in two contrast ratios. "low" and "medium"







# SFR - Sharpening

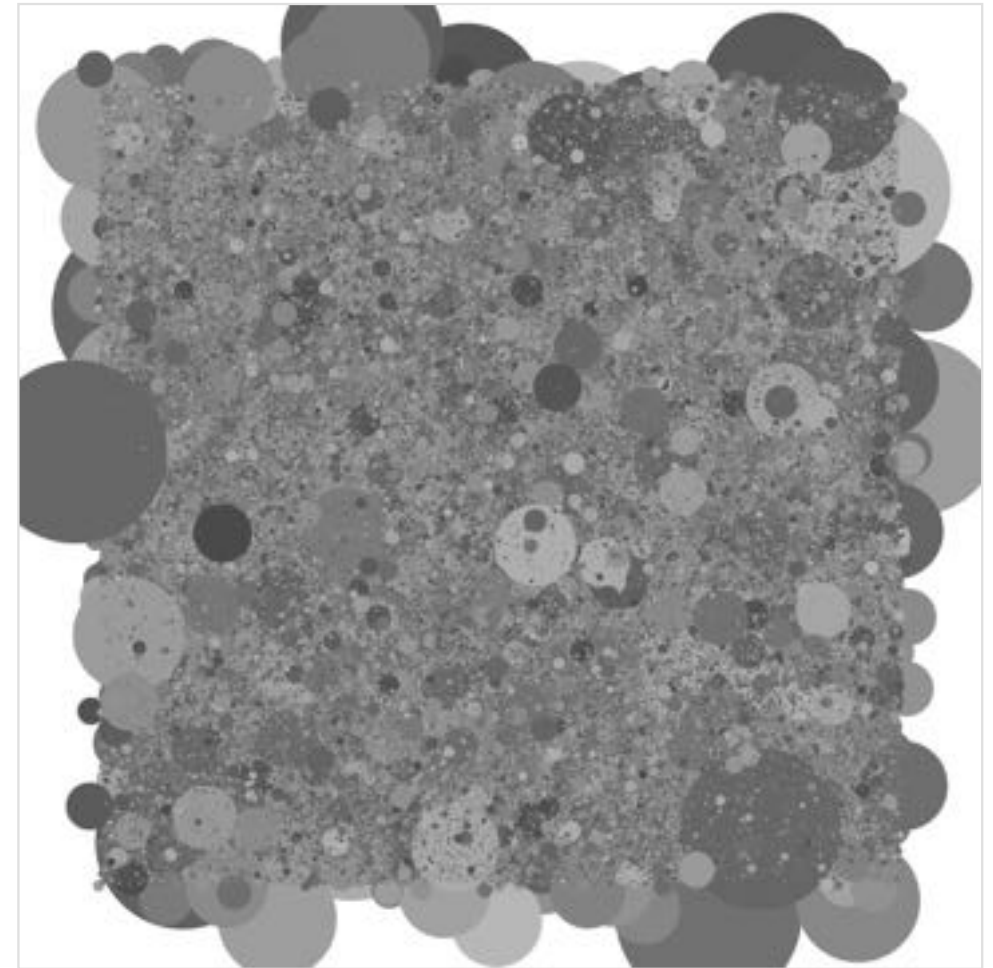




# Spatial Matching



Let the pattern cover only a small part of the image to reduce the influence of distortion.



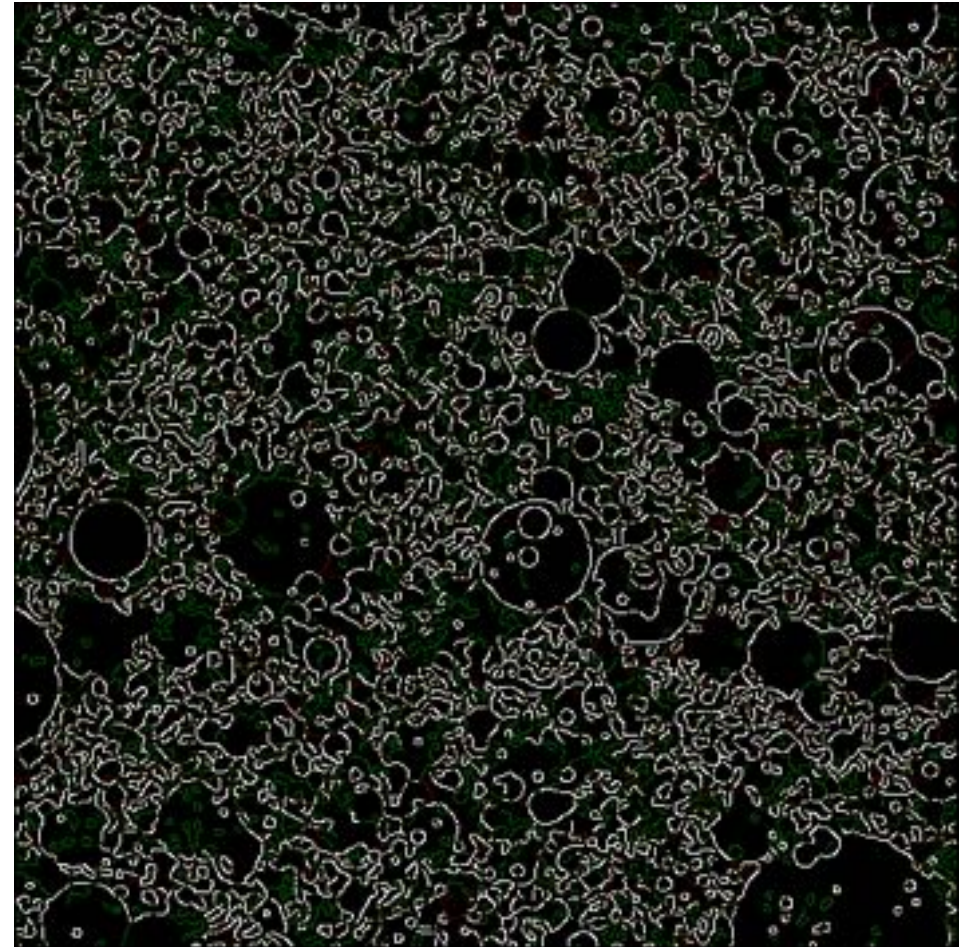
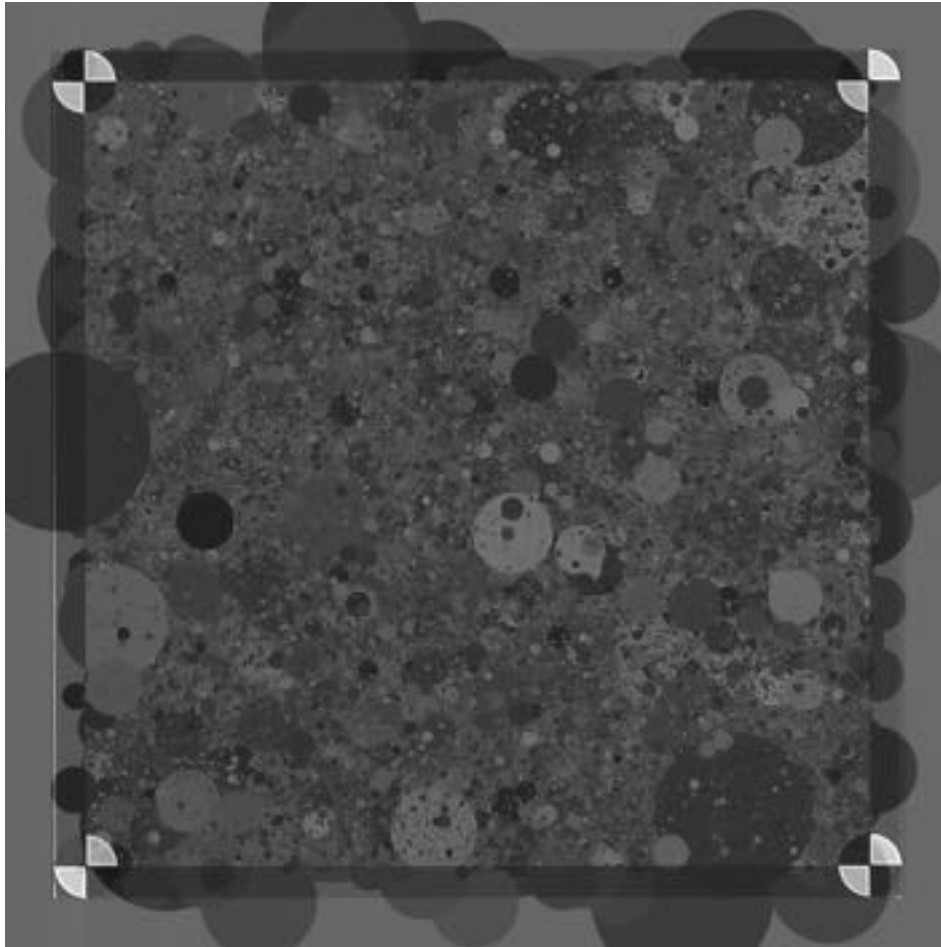
Create projection matrix from position of marker and apply to reference data.







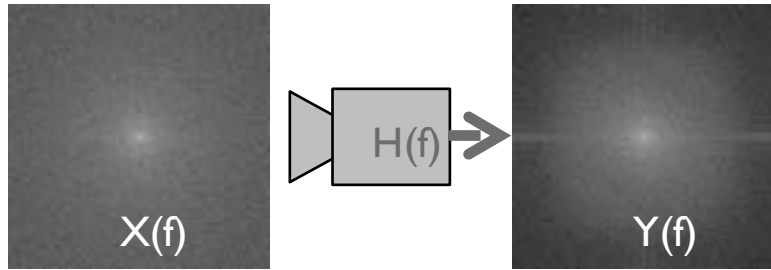
# Spatial Matching







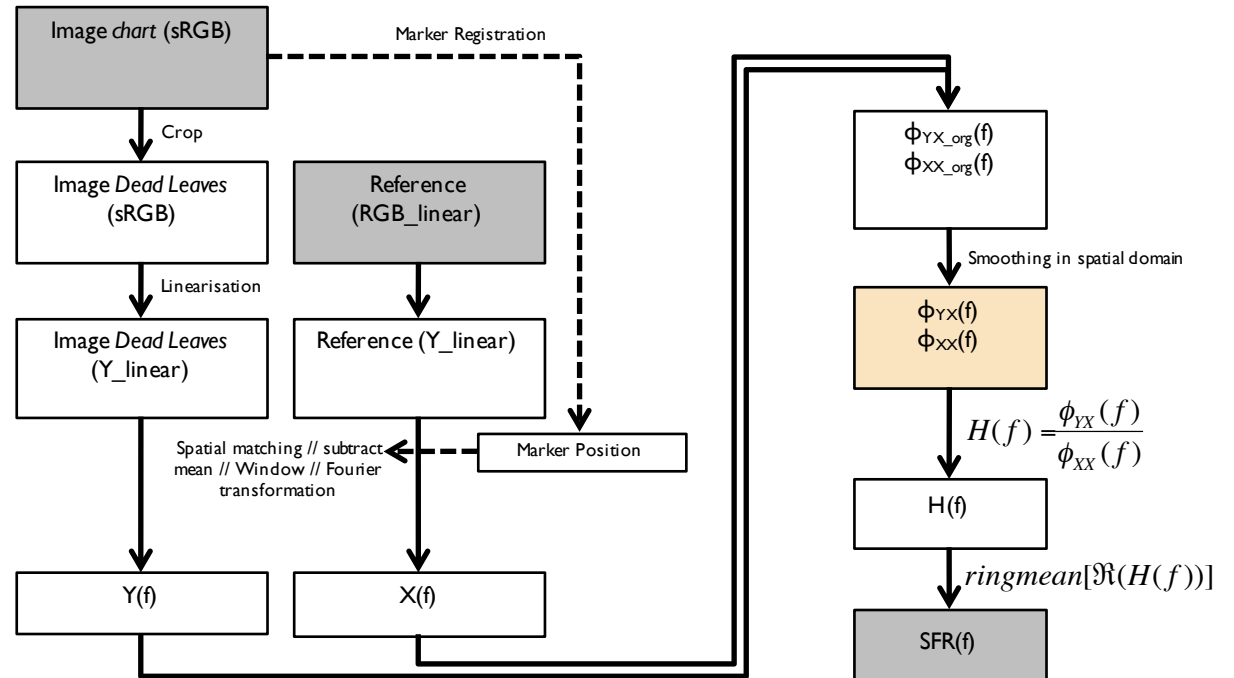
# Dead Leaves \_ cross



full transfer function available!

$$H(f) = \frac{\phi_{YX}(f)}{\phi_{XX}(f)}$$

$\phi_{XX}(f)$ : power spectrum of the input  
 $\phi_{YX}(f)$ : cross power spectrum of input and output



Based on the work of Image Engineering

“Description of texture loss using the dead leaves target: current issues and a new intrinsic approach”, Kirk, Herzer, Artmann, Kunz, Proc. SPIE 9023, Digital Photography X, 90230C (7 March 2014); doi: 10.1117/12.2039689

The only Dead Leaves approach that really describes the texture loss!





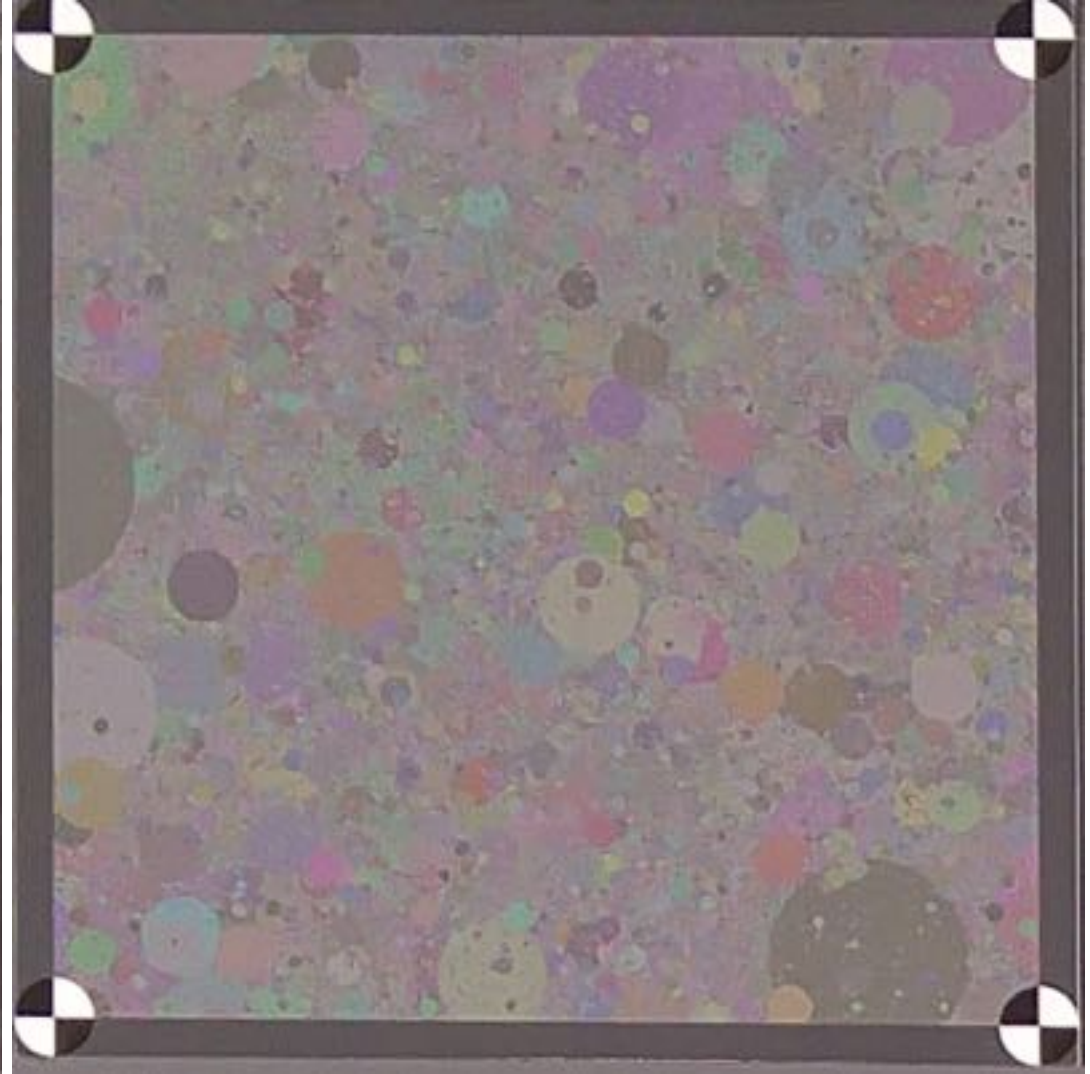
# Texture loss

The latest approach (DeadLeaves\_cross)

“-4EV” – low contrast



“bright” – low contrast

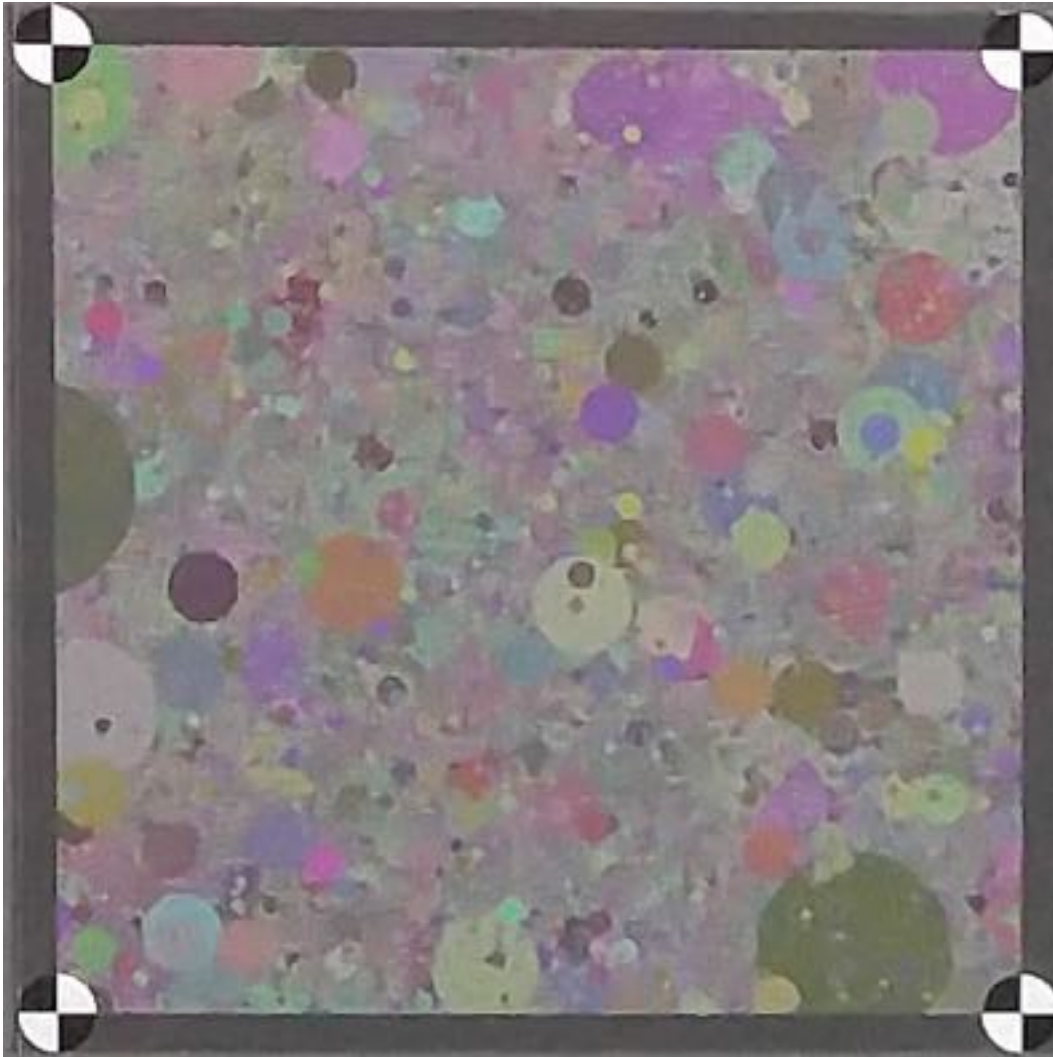




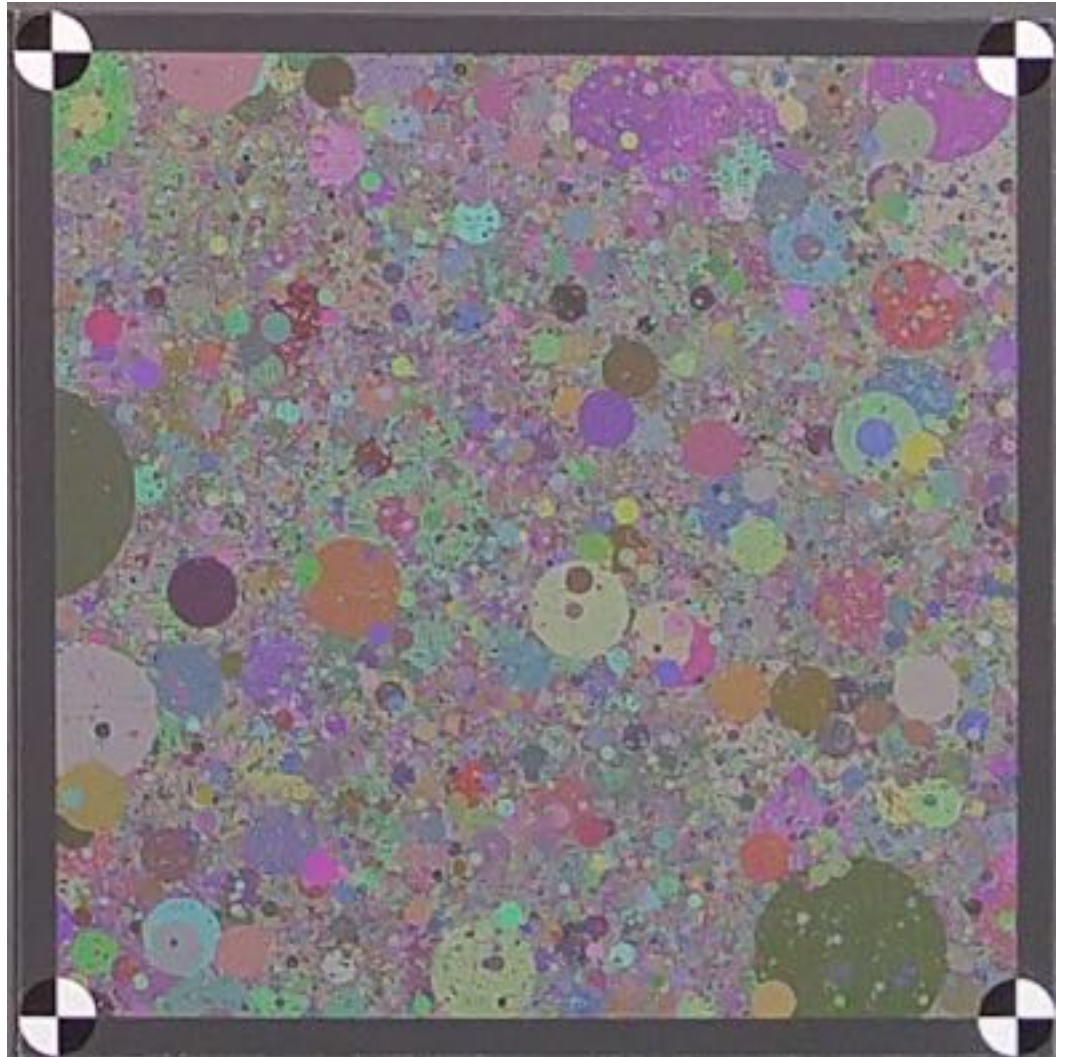
# Texture loss

The latest approach (DeadLeaves\_cross)

“-4EV” – high contrast

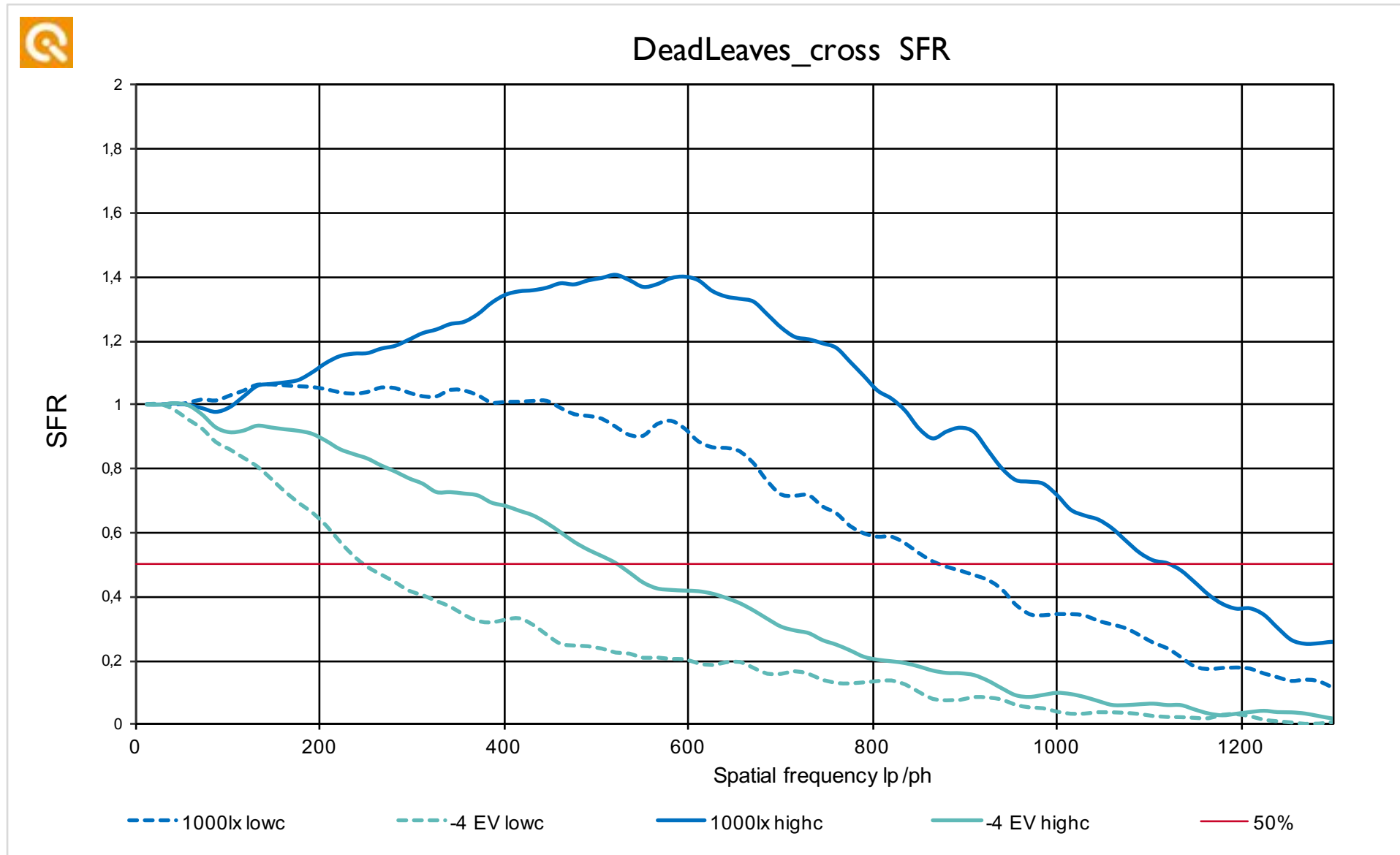


“bright” – high contrast





## The latest approach (DeadLeaves\_cross)







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**Image Engineering**

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**Documents**

- All
- Conference papers**
- Diploma thesis
- Technotes
- Video tutorials
- White paper

## Image quality assessment using the dead leaves target

Conference Papers 13 Mar 2015

Experience with the latest approach and further investigations. Electronic Imaging Conference 2015 - Uwe Artmann (Image Engineering)

[READ PAPER](#)

## Description of texture loss using the dead leaves target

Conference Papers 15 Mar 2014

Current issues and a new intrinsic approach. Electronic Imaging Conference 2014 - Leonie Kirk, Philip Herzer, Uwe Artmann (Image Engineering) and Dietmar Kunz (Cologne University of Applied Sciences)

[READ PAPER](#)

<http://www.image-engineering.de/library/conference-papers>

[www.image-engineering.de](http://www.image-engineering.de)







	Sinusoidal Siemens star	Slanted edge	Dead Leaves
Advantages	<ul style="list-style-type: none"><li>• Reliable measurement of limiting resolution</li><li>• Robust</li><li>• Visual interpretation</li></ul>	<ul style="list-style-type: none"><li>• Fast</li><li>• Easy way to measure sharpening</li></ul>	<ul style="list-style-type: none"><li>• Random pattern triggers “Texture loss”</li><li>• More “natural” than other structures</li></ul>
Utilization	Assessment of optical performance of devices	Assessment of signal processing of a device	Assessment of texture loss of a device





Aus der allgemeinen Messtechnik übernommen, wurde das Rauschen lange als „Signal-Rauschabstand“ (SNR) angegeben. Das Problem: Dies korreliert nicht mit der Rauschwahrnehmung

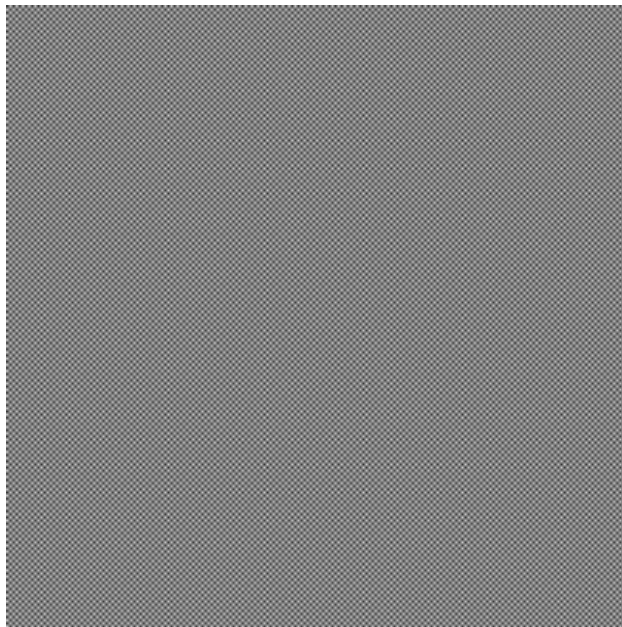


Unterschiedliche Rauschwahrnehmung – gleicher SNR

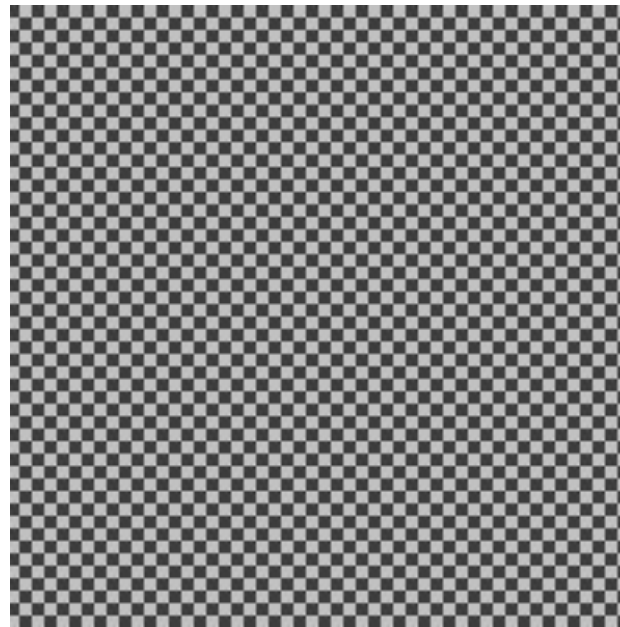




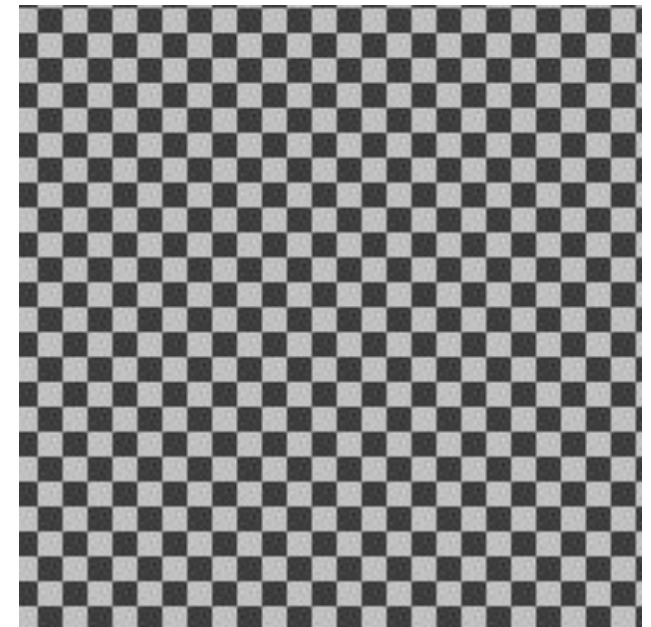
Aus der allgemeinen Messtechnik übernommen, wurde das Rauschen lange als „Signal-Rauschabstand“ (SNR) angegeben. Das Problem: Dies korreliert nicht mit der Rauschwahrnehmung



$\mu = 128$   
 $\sigma = 64$



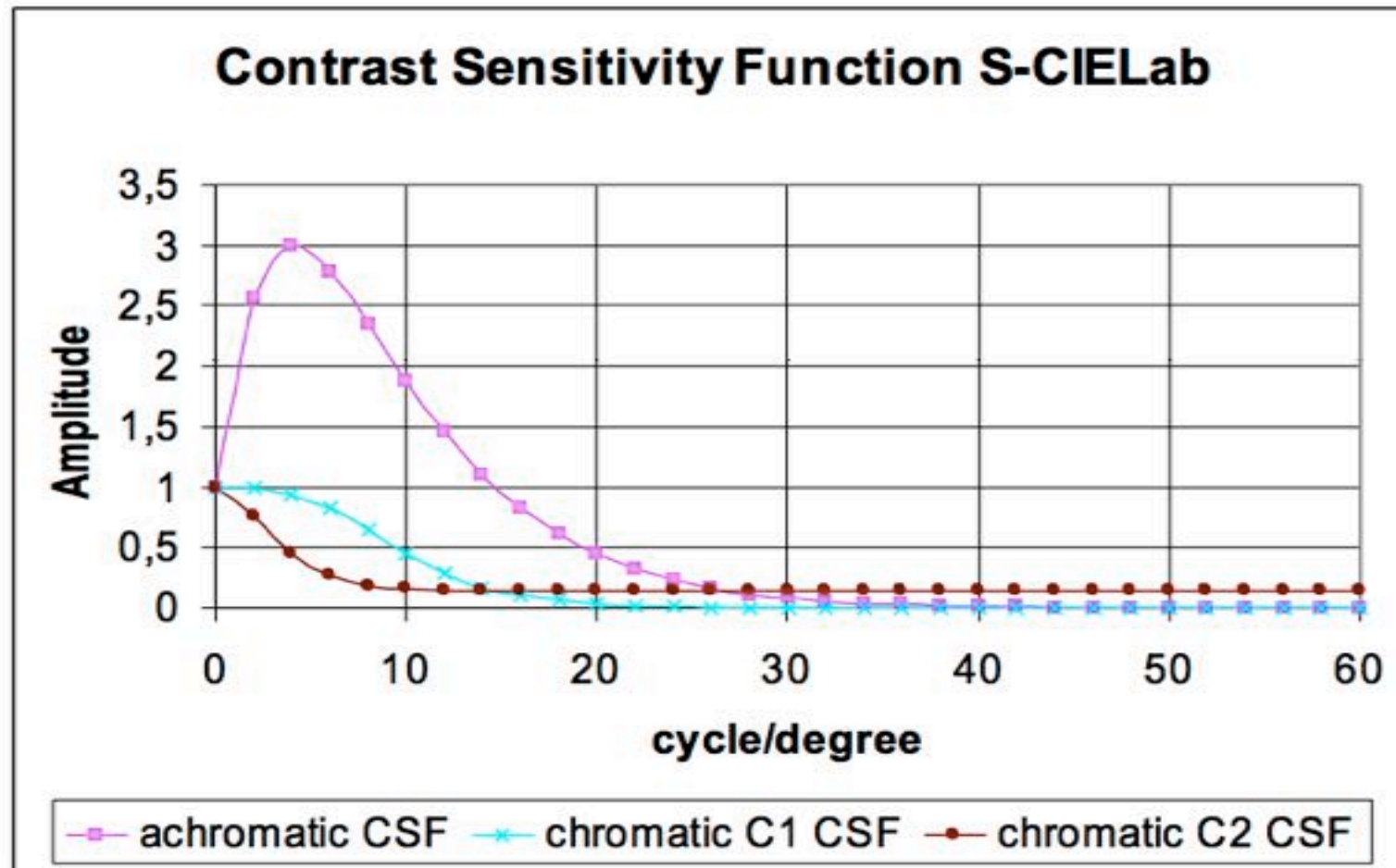
$\mu = 128$   
 $\sigma = 64$



$\mu = 128$   
 $\sigma = 64$

Unterschiedliche Rauschwahrnehmung – gleicher SNR





A  $C_1C_2$  – opponent space – a color space based on analysis of color receptors of human eye and of processing the resulting color signals

A – achromatic information

– only intensity, no color

$C_{1\&2}$  – color information

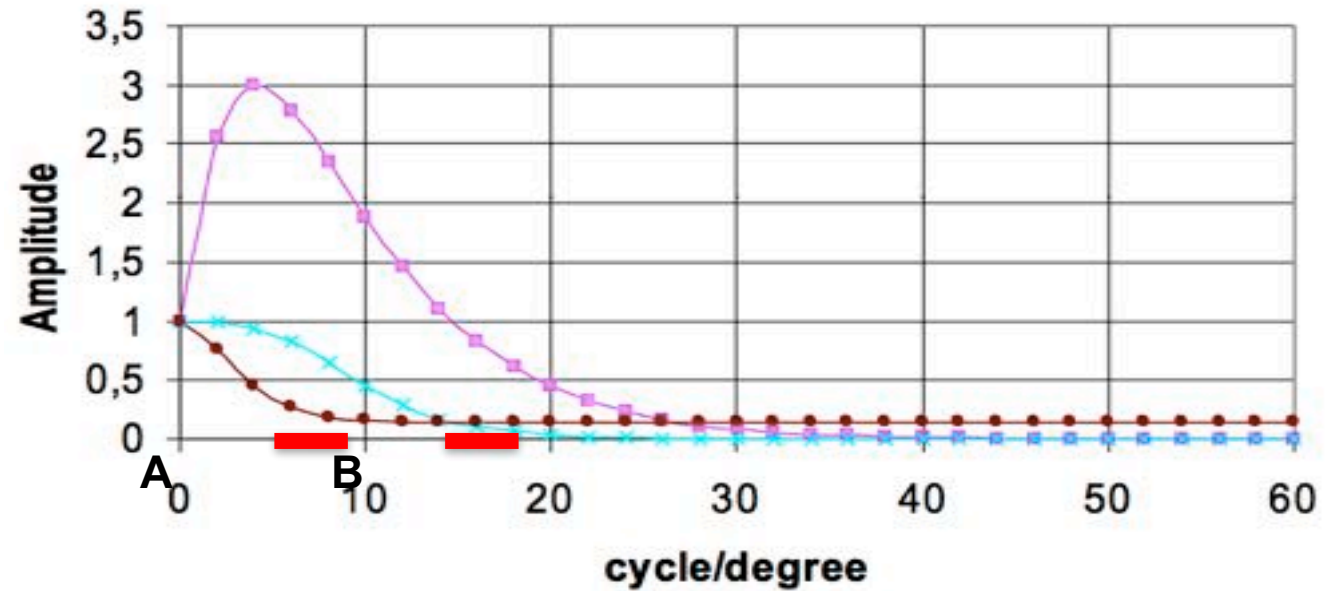
– only color, no intensity



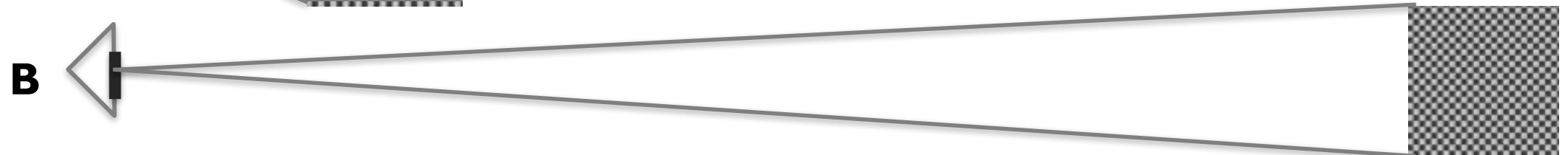
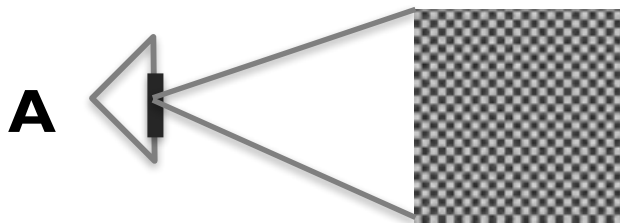


## Contrast Sensitivity Function S-CIELab

Die Rausch-  
wahrnehmung hängt  
von der  
Betrachtungs-  
bedingung ab !



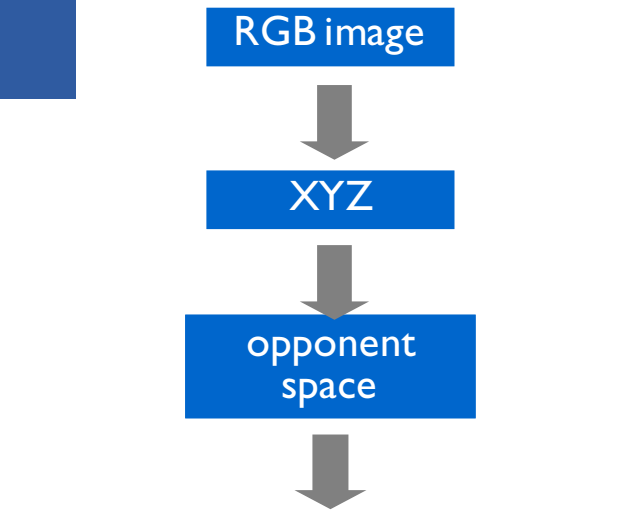
**A** – low cycle / degree – more noise visible  
**B** – higher cycle / degree – less noise visible





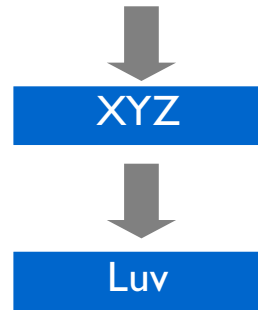


# Visual Noise



Gewichtung des Rauschens nach Wahrnehmung

(CSF) frequency filtering



the Luv color space is better suited for viewing smaller field than the Lab color space

weighted standard deviation

in the Luv the standard deviation is calculated for every patch and weighted with the aid of the formula:  $1.000L + 0.8520u + 0.3230v$





# Optische Bildstabilisierung





# Optische Bildstabilisierung



STEVE OFF  
image stabilization OFF



STEVE ON  
image stabilization OFF



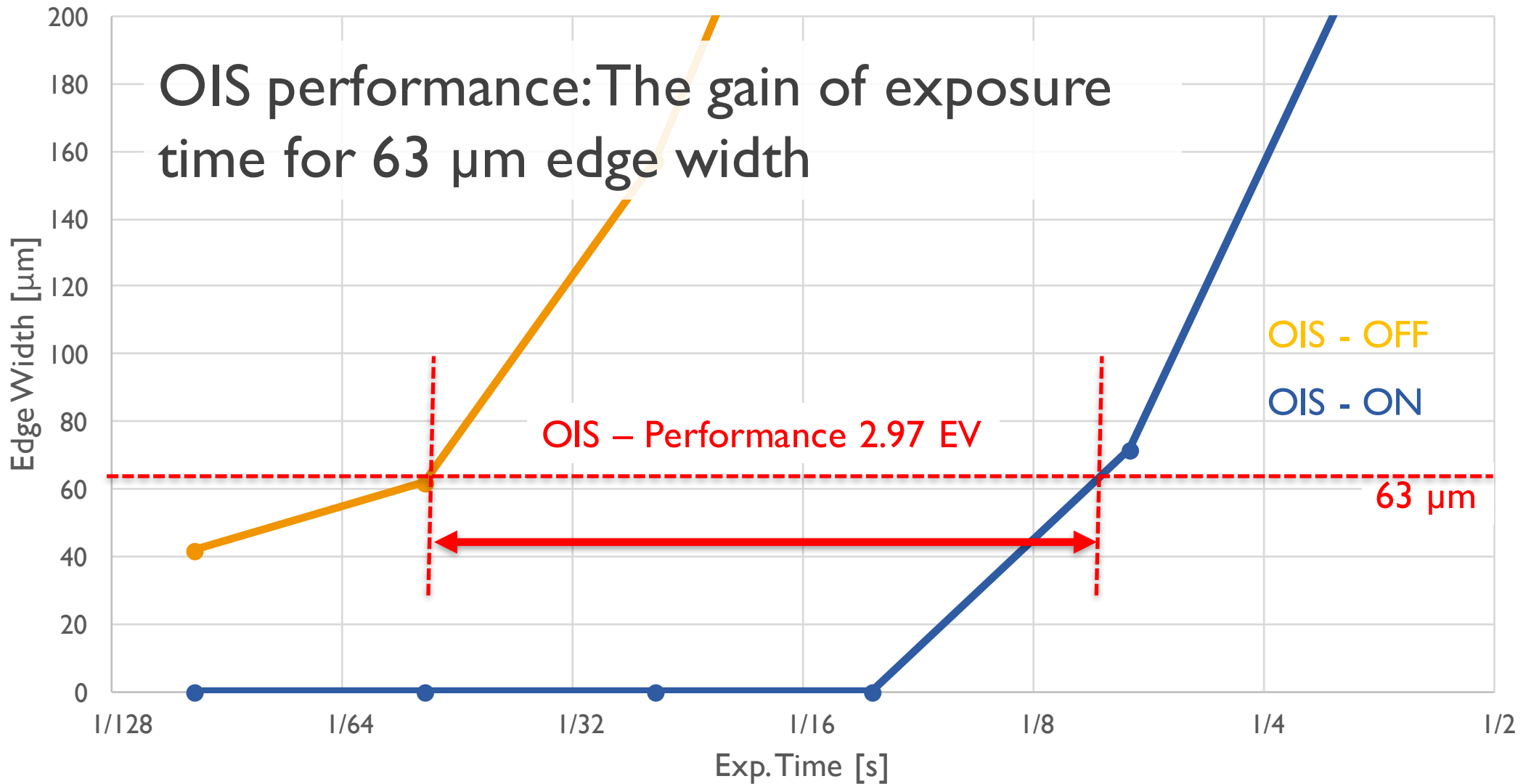
STEVE ON  
image stabilization ON



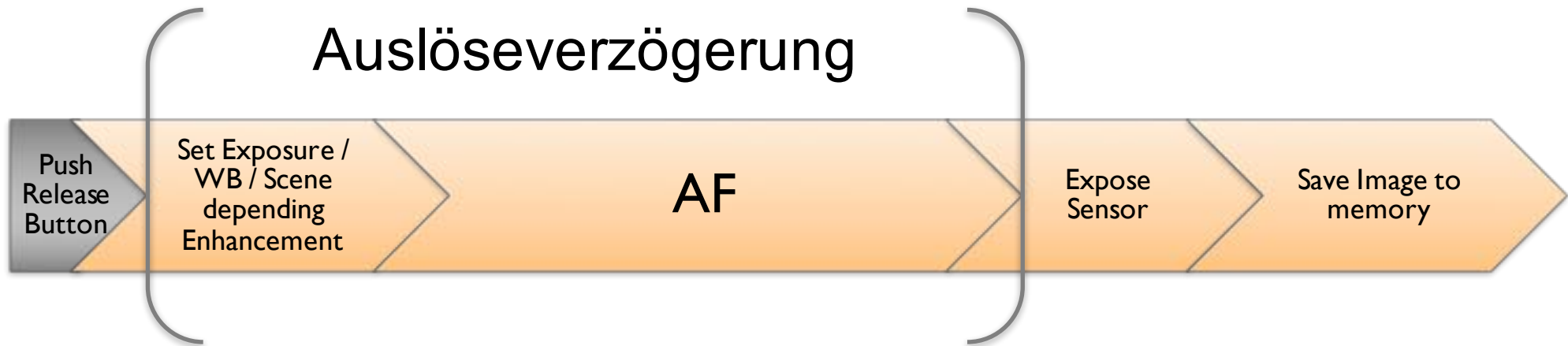


# Optische Bildstabilisierung

CIPA DC-X011 – SONY NEX-7 - E 50mm F1,8 OSS







Definition: Die Zeit die zwischen dem Druck auf den Auslöser und dem beginn der Belichtung.





Definition: Die Zeit die zwischen dem Druck auf den Auslöser und dem beginn der Belichtung.





# Time Measurement - Method



ISO 15781 - Zeitenmessung





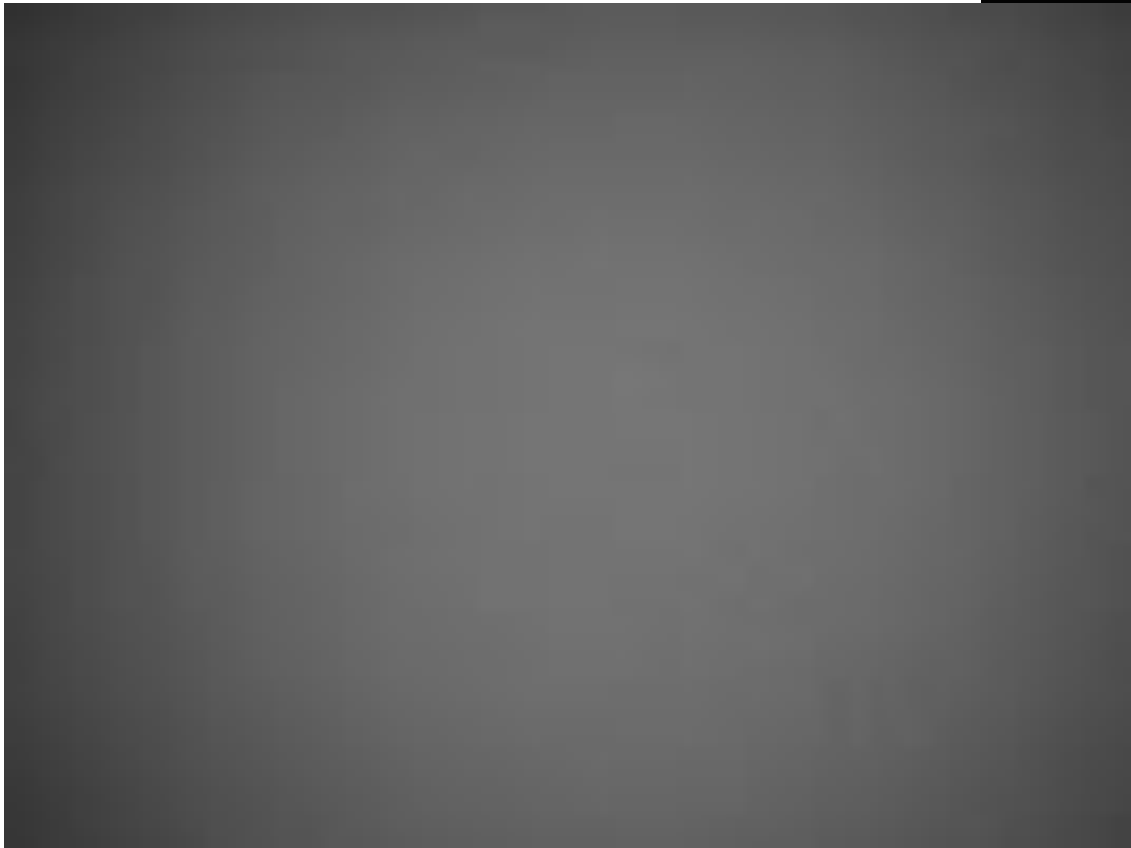
# Vignettierung







# Vignettierung



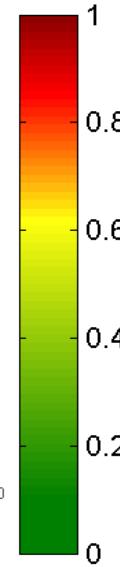
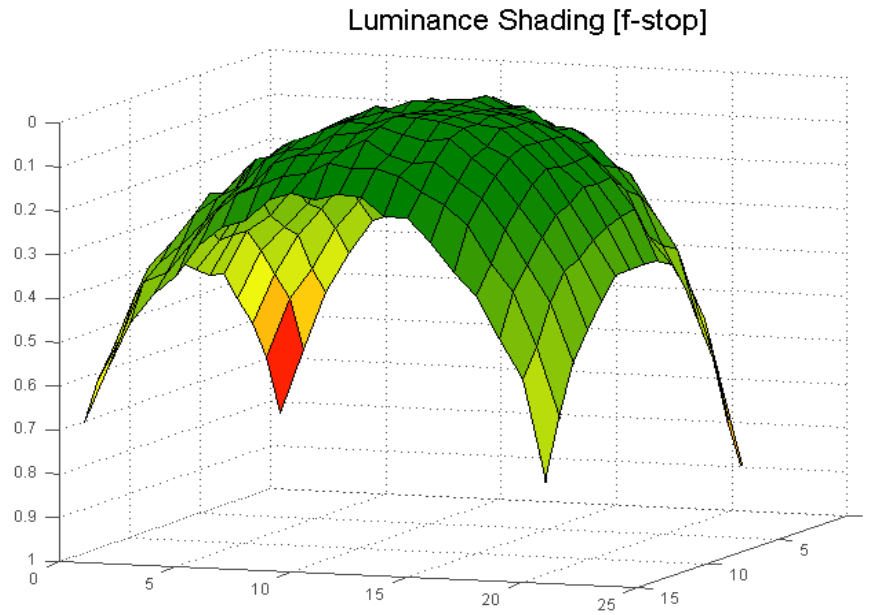
Vignettierung führt zu einem Randlichtabfall – die Bildecken sind dunkler als die Bildmitte.

Ein Problem so alt wie die Fotografie.





# Vignettierung



YI\_CAL3.jpg

Make	XIAOYI
Model	YDXJ1
Width	4608
Height	3456
Time	480
F-Stop	2.8
ISO	171
f[mm]	2.7
EV	0.000
Serial:	
Lens:	
Firmware:	Ver.1.0.000
Illumination [lux]:	
Object Distance [m]	
Laboratory:	
Operator:	



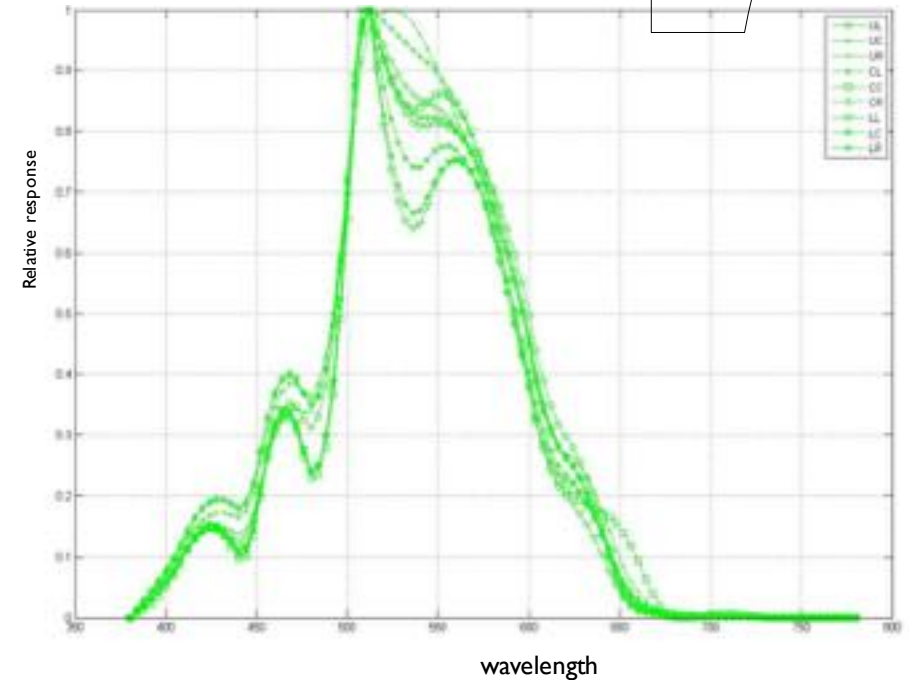
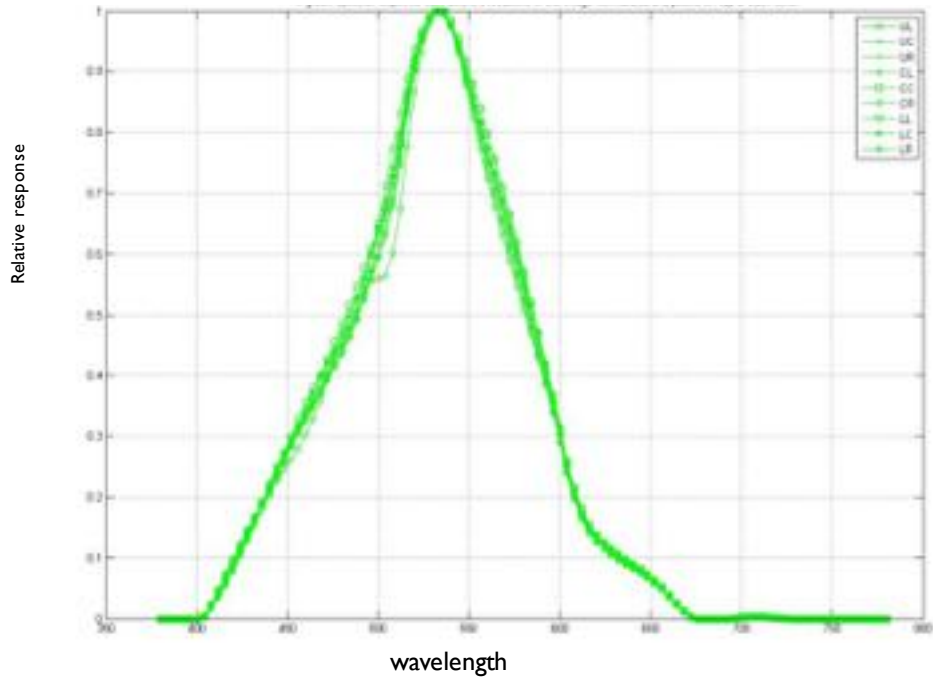
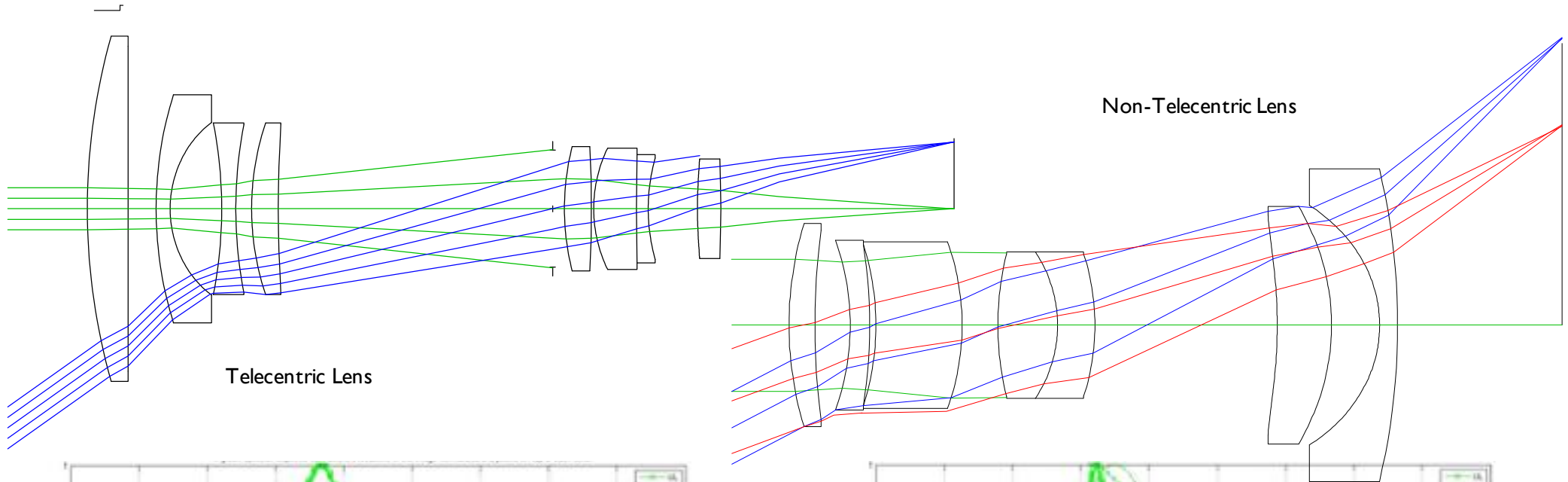
Luminance	
Shading[f-stop]	0.9
Shading[%]	24.7
dL	13.6
percentilesY[DV]	-22.2/-1.2/-0.3/0.1
percentilesY[f-stop]	-0.54/-0.03/-0.01/0.00
Color	
dEab	9.8
dC	8.8
dG-R[DV]	27.4
dG-B[DV]	9.1
R/G&B/G	1.04/0.83
Noise	
dSNR[dB]	9.1
dVNSet1	2.0
dVNSet2	1.7
dVNSet3	1.8







# Color Shading





# Color Shading



Color-Shading wird auf einer homogenen und spektral gleichmäßigen Fläche gemessen.

Die Angabe erfolgt üblicherweise in  $\Delta E_{ab}$







Bei klassischen Objektiven gibt es zwei Arten von Verzeichnung



Kissen-Verzeichnung

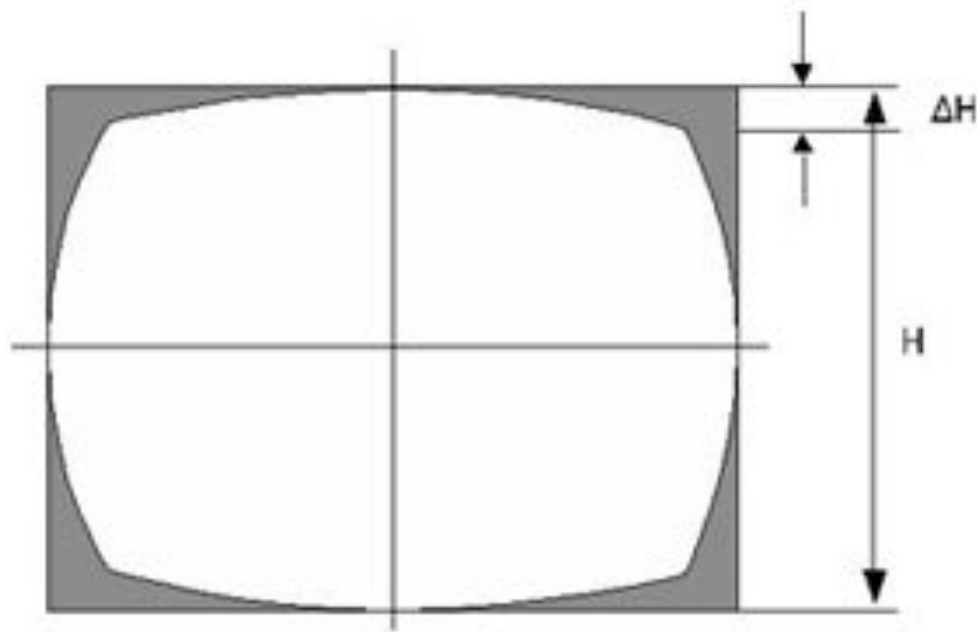


Tonnen-Verzeichnung



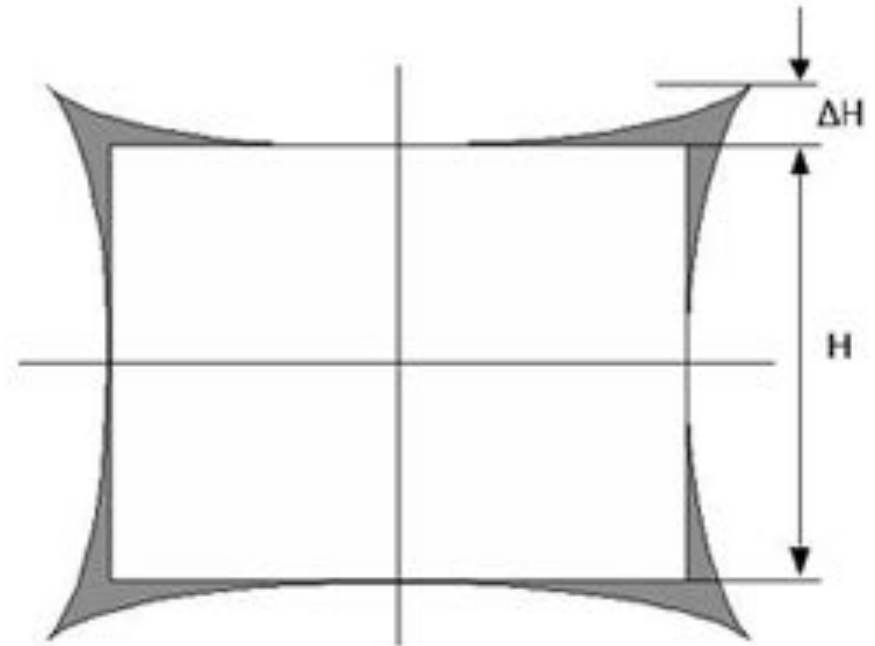


$$D_{TV}[\%] = \frac{\Delta H}{H} \cdot 100$$



picture height distortion  
with barrel shape (negative)

maximum picture height



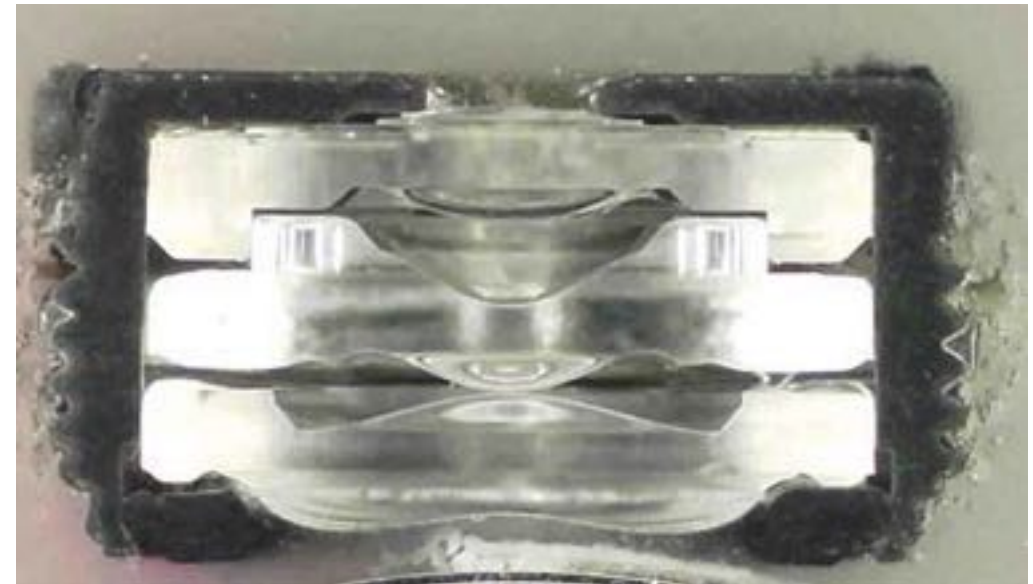
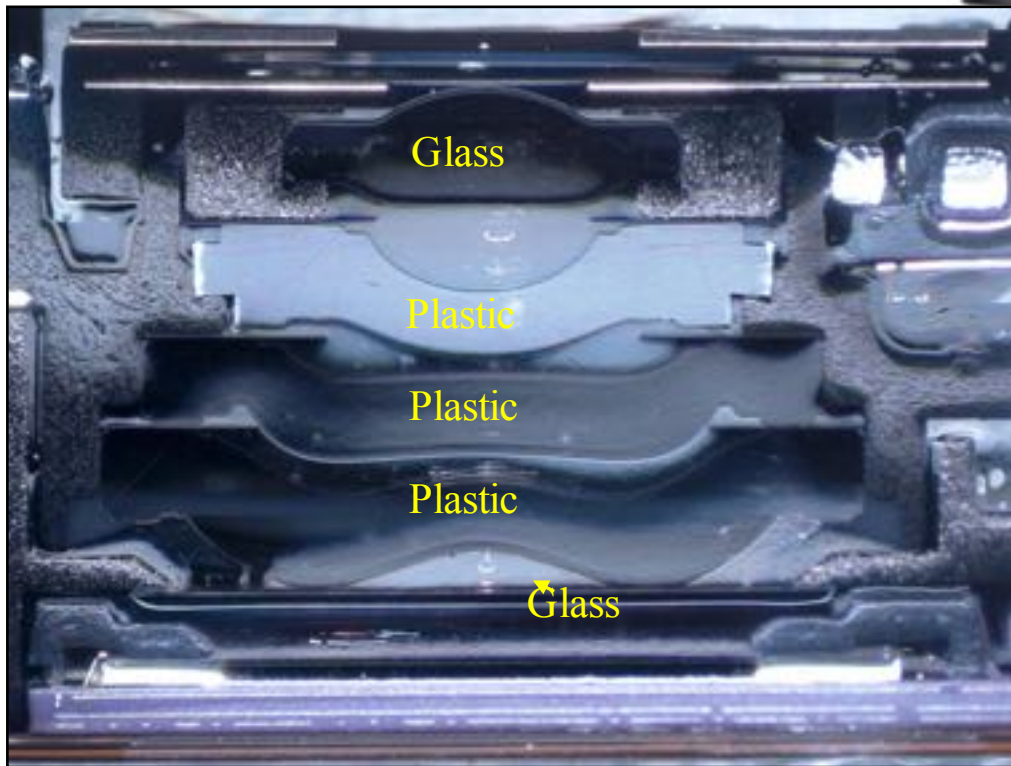
picture height distortion  
with pincushion shape (positive)

minimum picture height





Leica Summilux 35mm f1.4



Mobiltelefon

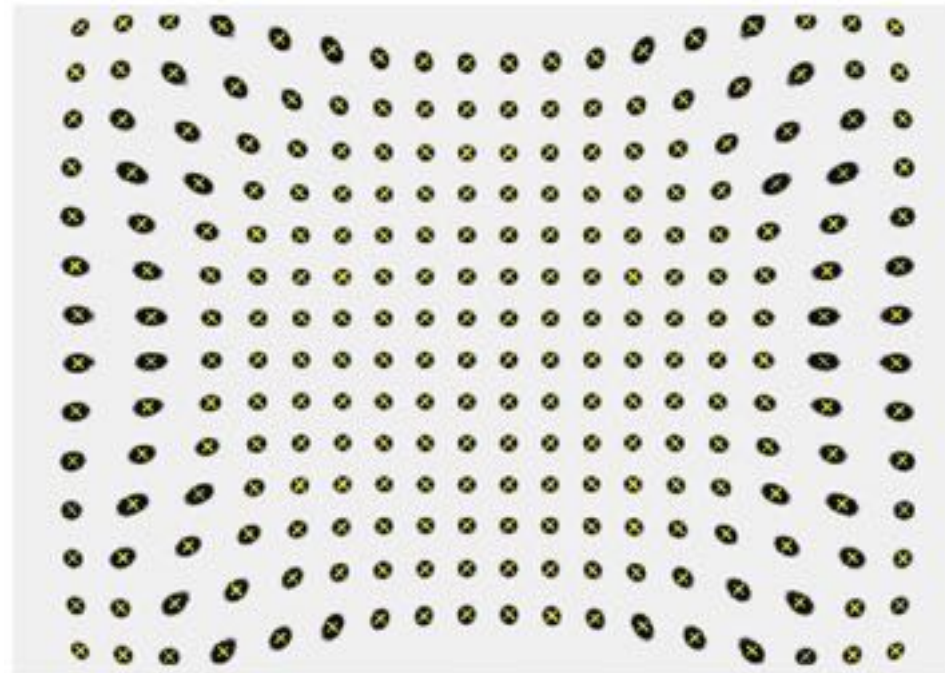
Moderne Optiken in Mobiltelefone kennen Zwischenformen







Mischform – “Wave Distortion” oder “Moustache Distortion”



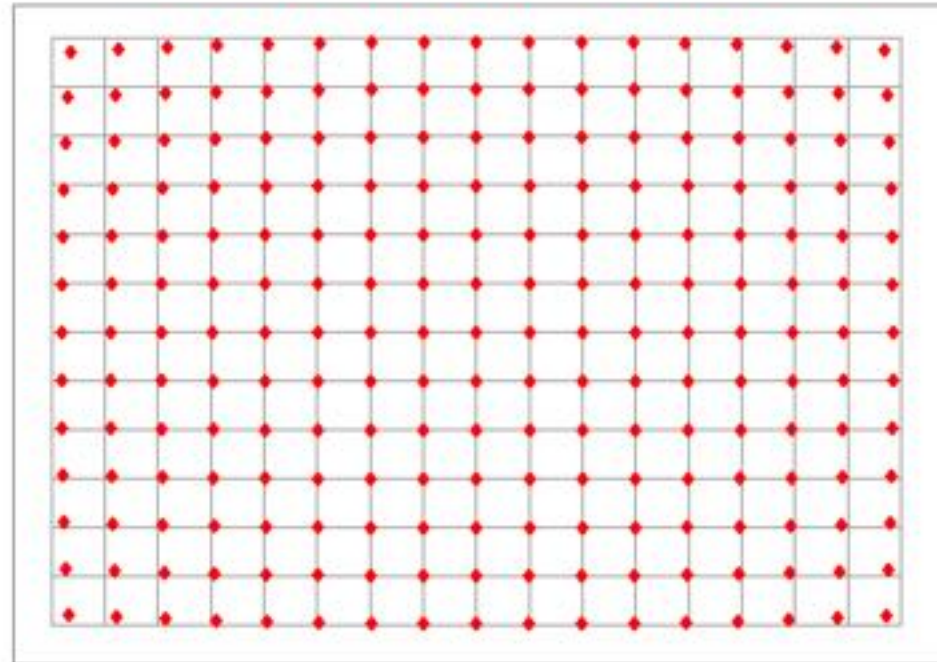
example for wave distortion



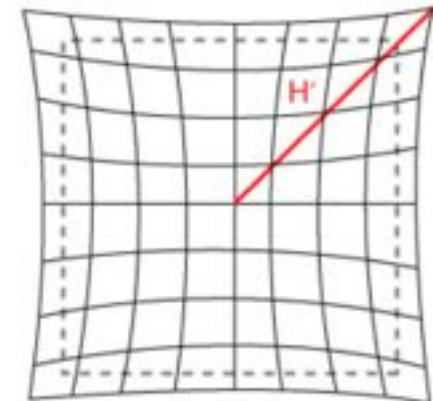
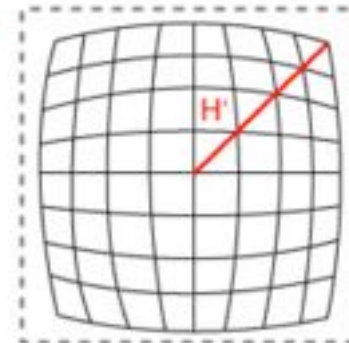
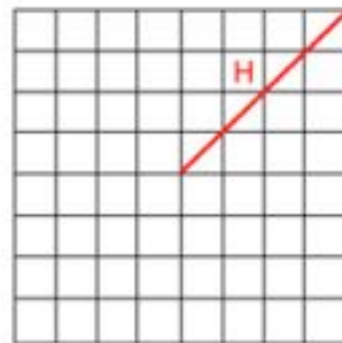


## Local Geometric Distortion

1. Detection von Kreuzen im Bild /Subpixel
2. Berechnung des idealen Gitter
3. Berechnung der Differenz von idealer Position zu realer Position für alle Kreuze



$$D[\%] = \frac{(H' - H)}{H} \cdot 100$$





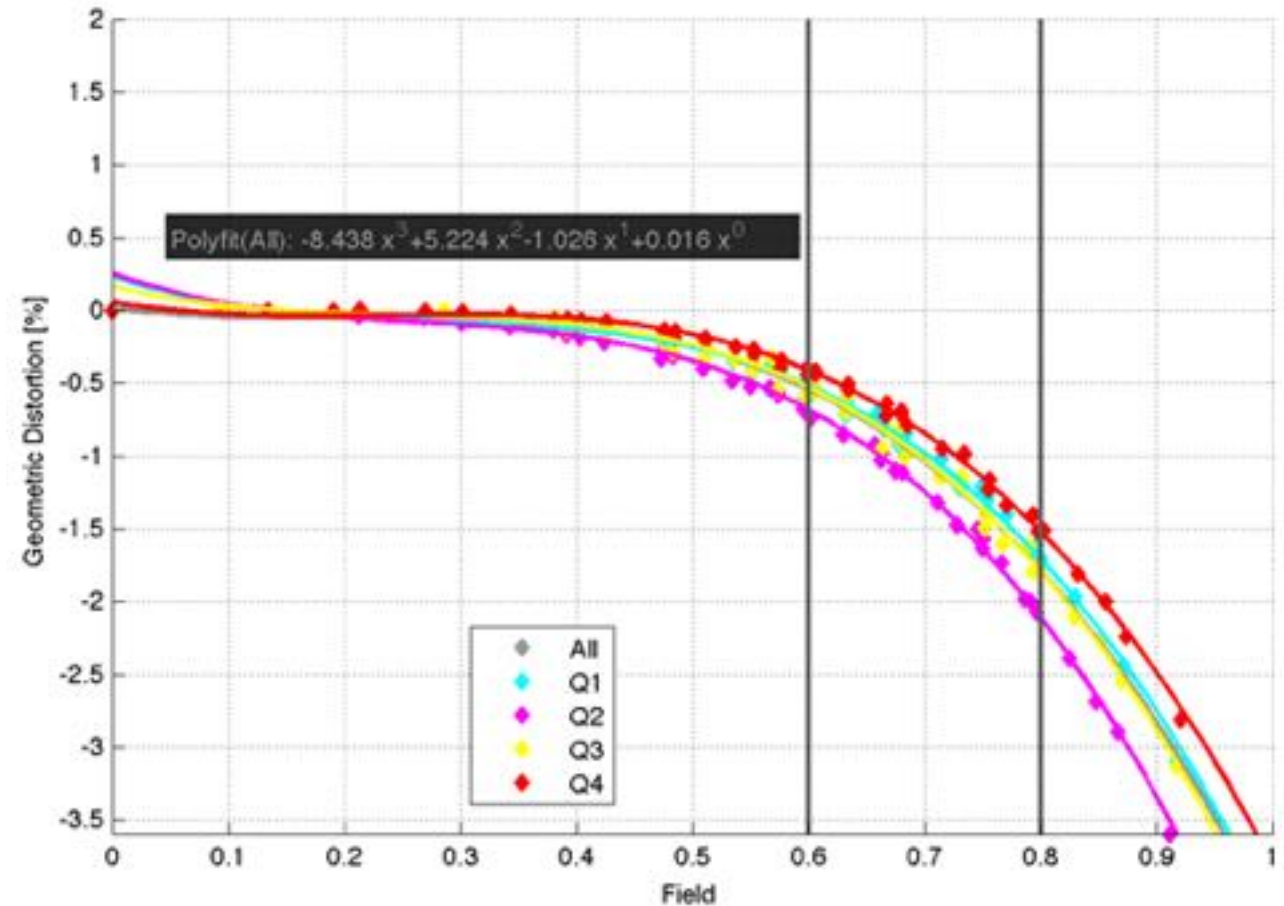


## Local Geometric Distortion

1. Detektion von Kreuzen im Bild /Subpixel
2. Berechnung des idealen Gitter
3. Berechnung der Differenz von idealer Position zu realer Position für alle Kreuze



the four quadrants (Q1, Q2, Q3, Q4)





# Auto White Balance

Was ist ein guter Weißabgleich ?





# Auto White Balance

Was ist ein guter Weißabgleich ?





# 360° Kameras



Paralaxe / Anschlussproblem bei Multi-Kamerasystemen







# 360° Kameras



Farbübergänge bei Multi-Kamerasystemen







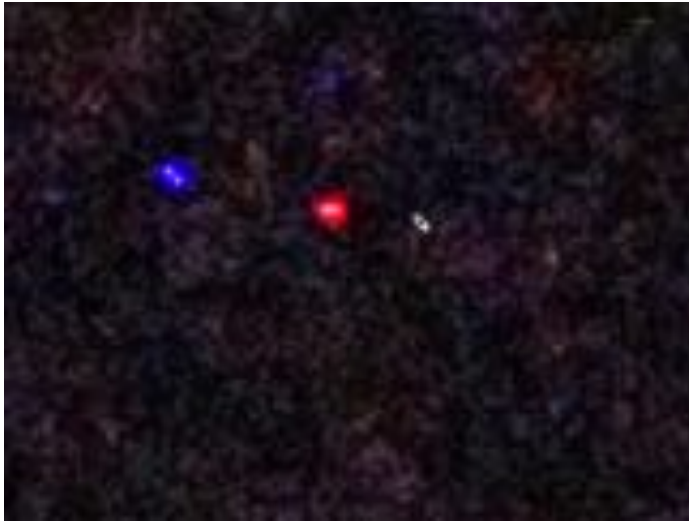
- Kameras werden besser – Messverfahren müssen mithalten
- Neue Technologien erfordern neue Messverfahren
- **Was der Kunde nicht weiß... Den Finger in die Wunde legen**





JPEG

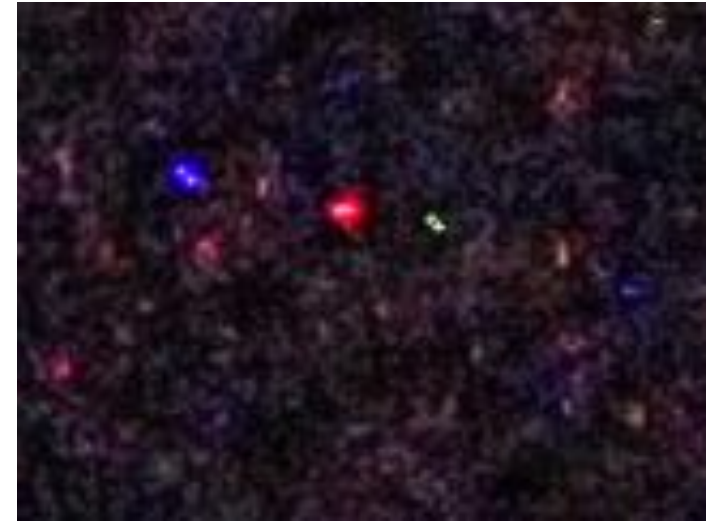
Detailvergrößerung Schwarzbild



Langzeit ohne NR



Langzeit mit NR



Langzeit mit NR (abgebrochen)

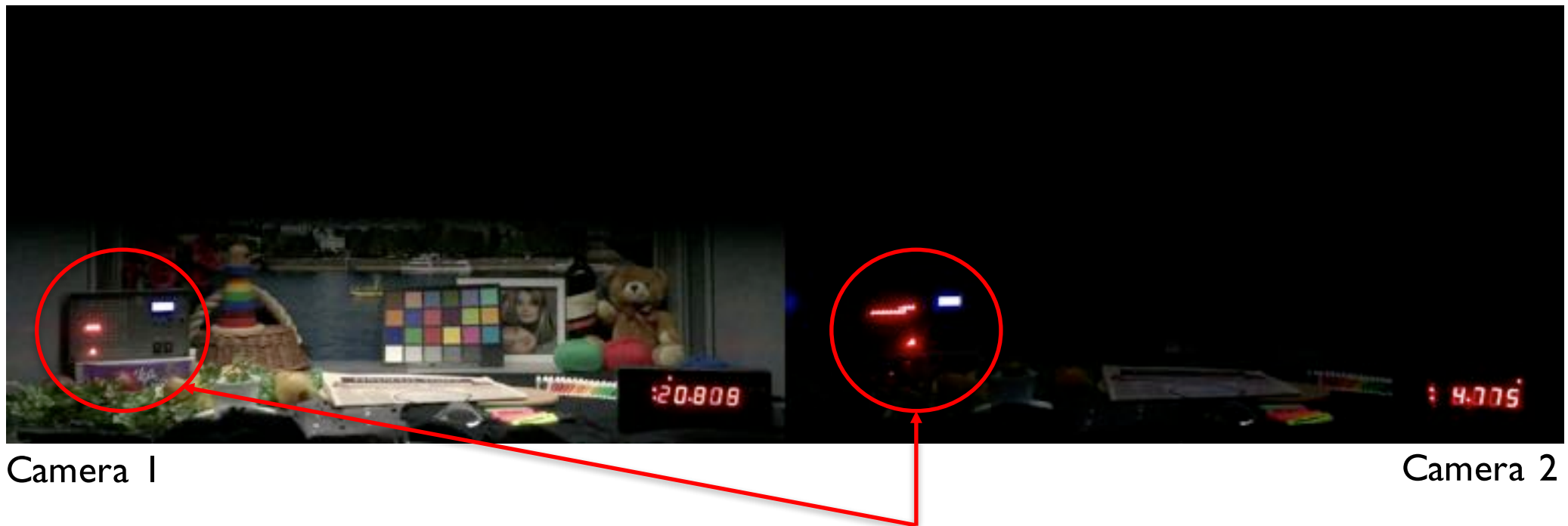


RAW





lightSTUDIO – Testszene mit anpassbaren Lichtbedingungen



Es werden immer 30 Bilder/s in die Datei geschrieben...

